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Initial Instabilities of a Granular Bed Sheared by a Turbulent Liquid Flow: Length-Scale Determination

The transport of granular matter by a fluid flow is frequently found in nature and in industry. When the shear stresses exerted by the fluid flow on a granular bed are bounded to some limits, a mobile granular layer known as bed-load takes place, in which the grains stay in contact with the fixed part of the granular bed. Under these conditions, an initially flat granular bed may be unstable, generating ripples and dunes, such as those observed in deserts, but also in pipelines conveying sand. There are evidences that these forms have a typical length correlated to their initial wavelength. So, the length-scale of the initial linear instabilities is a key point to understand the typical structures observed. This paper presents a theoretical study of the initial instabilities on a granular bed sheared by a turbulent liquid flow without free-surface effects, when bed-load is present. This study consists of a linear stability analysis, taking into consideration fluid flow, relaxation and gravity effects, and it is compared to published experimental data. It is proposed here, differently from many previous studies, that the initial wavelength of bed-forms varies with flow conditions when the fluid is a liquid.

Keywords: two-phase flow, granular bed, bed-load, instabilities, pattern formation

Introduction

The transport of solid particles entrained by a fluid flow is frequently found in nature and in industry. It is present, for example, in the erosion of river banks, in the displacement of desert dunes and in hydrocarbon pipelines conveying sand. When shear stresses exerted by the fluid flow on the granular bed are able to move some grains, but are relatively small compared to the grains weight, the flow is not able to transport grains as a suspension. Instead, a mobile layer of grains known as bed-load takes place in which the grains stay in contact with the fixed part of the granular bed. The thickness of this mobile layer is of a few grain diameters (Bagnold, 1941; Raudkivi, 1976).

Under the fluid flow, a flat granular bed may become unstable and give rise to bed-forms. These forms are initially twodimensional, but they may grow and generate patterns such as dunes. For instance, such instabilities give rise to the migrating aeolian dunes observed in nature, which are one of the mechanisms of the expansion of deserts (Bagnold, 1941). The aquatic dunes observed on the bed of some rivers are another example. These forms create a supplementary friction between the bed and the water, affecting the water depth and being related to flood problems. In cases where their size is comparable to the water depth, water flows can experiment strong depth variations, seriously affecting navigation (Engelund and Fredsoe, 1982). In industry, examples are mostly related to closed-conduit flows conveying grains, such as hydrocarbon pipelines conveying sand. In such cases, the bed-forms generate not only supplementary pressure loss, but also pressure and flow rate transients (Kuru et al., 1995; Franklin, 2008).

The stability of a granular bed is given by the balance between local grains erosion and deposition. If there is erosion at the crests of the granular bed, the amplitude of initial bed undulations decreases and the bed is stable. Otherwise, the bed is unstable. If there is neither erosion nor deposition at the crests, there is neutral stability.

The regions of erosion and deposition can be found from the mass conservation of grains. The mass conservation implies that there is erosion in regions where the gradient of the flow rate of grains is positive and deposition where it is negative, so that the phase lag between the flow rate of grains and the bed-form is a

stability criterion. If the maximum of the flow rate of grains is upstream a crest, there must be deposition at the crest and the bed is unstable, otherwise the bed is stable. To answer the stability question, the mechanisms creating a phase lag between the shape of the granular bed and the flow rate of grains need to be known. They are three: the fluid flow perturbation by the shape of the bed, the relaxation effects related to the grains and the gravity effects. The fluid flow perturbation is known to be the unstable mechanism (Jackson et al., 1975; Hunt et al., 1988 and Weng et al., 1991), and the relaxation and the gravity effects are the stable mechanisms (Valance and Langlois (2005) and Charru (2006) in the case of viscous flows).

A "hydrodynamic stability" approach (Drazin and Reid, 2004) may be employed to address the stability of a sheared granular bed if some assumptions are made (described in the following sections). Many works on the stability of granular beds sheared by a fluid were made in the last decades using this approach (Kennedy, 1963; Engelund, 1970; Richards, 1980; Elbelrhiti et al., 2005 and Claudin and Andreotti, 2006, for instance). A remarkable overview of this kind of work can be found in Engelund and Fredsoe (1982).

It must be noted that the granular matter in itself is one of the challenging problems in physics today, so that our knowledge about it is confined to fundamental physics (Duran, 1999). As with any fundamental problem of this kind, the interest here is in finding correlations and tendencies between the relevant parameters, both theoretically and experimentally. Determination of the precise values of wavelength, growth rate and celerity as observed in nature is not possible yet.

This paper presents a stability analysis for the specific case of granular beds sheared by turbulent boundary-layers of liquids. The purpose of this analysis is to obtain some tendencies for the growth rate, the celerity and the length-scale of the initial instabilities appearing on the granular bed in this specific fluid flow condition. In particular, this analysis shed light on the length-scale of the generated bed-forms whenever the fluid is a liquid, and it seems to be corroborated by some published experimental data. Figure 1 presents the dimensions involved in the studied problem.

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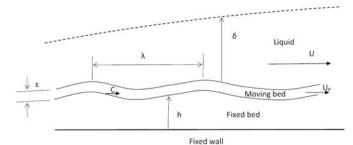


Figure 1. Granular bed sheared by a fluid flow. U is the mean velocity of the fluid, U_P is the mean velocity of grains, h is the height of the fixed bed, ϵ is thickness of the moving bed, c is the celerity of the bed-forms, λ is the wavelength of the bed-forms and δ is the boundary-layer thickness. In the present paper, c << U_P << U, ϵ << h, Re $_{\delta}$ = δ u-/ v > 10² and, if η is the amplitude of the bed-forms, η/λ << 1 and η/δ << 1. u- is the friction velocity (defined in the following sections) and v is the kinematic viscosity.

The next two sections present a linear stability analysis for a granular bed sheared by a turbulent liquid flow (without free-surface effects). The obtained wavelengths are compared in the following section to some published experimental data. A conclusion section follows.

Nomenclature

A= constant В = constant= phase velocity, m.s⁻¹ d = mean grain diameter, m = acceleration of gravity, m.s⁻² = channel height, m = local height of the granular bed, m = imaginary number k = wave-number, m⁻¹ L= length-scale, m Q = volumetric flow rate of grains by unit of width, in the basic state, m².s⁻¹ = local volumetric flow rate of grains by unit of width, $m^2 \cdot s^{-1}$ = fluid velocity, m.s = shear velocity, m.s⁻¹ u_* U_{S} = grain settling velocity, m.s⁻¹ U_p = mean grain velocity, m.s⁻¹ = Reynolds number (Re = HU/V)Ŕе = friction Reynolds number $\left(Re_{\delta} = \frac{\delta u_*}{V}\right)$ Re_{δ} = particle Reynolds number $\left(Re_p = d^2 \frac{\tau}{\nu\mu}\right)$ Re_{v} = settling Reynolds number $\binom{Re_S}{V}$ Re. t = time. s= horizontal (longitudinal) coordinate, m x v = vertical coordinate, m

Greek Symbols

 v_0

= rugosity height, m

= boundary-layer thickness, m δ = thickness of the moving bed, m 3 = amplitude of the initial instabilities, m η = von Kármán constant κ = wavelength of the initial instabilities, m = dynamic viscosity, Pa.s $= density, kg.m^{-3}$ ρ = growth rate, s^{-1} σ = shear stress, Pa τ = kinematic viscosity, $m^2.s^{-1}$

 ξ = integration variable, m ω = frequency, s^{-1} Subscripts

Subscripts

d relative to deposition drag relative to the inertial scale

dune relative to a dune

g relative to the acceleration of gravity

k relative to the Fourier space

max relative to the most unstable (amplified) mode

0 relative to the basic state

p relative to grains

s relative to settling

sat relative to the saturated regime

x relative to the real space

Superscripts

^ perturbation

Linear Stability Model

This paper presents a stability analysis of the initial bed-forms on a granular bed under a turbulent liquid flow, without free-surface effects. The analysis presented here is two-dimensional, which is justified by taking into consideration the Squire's Theorem for parallel flows (Drazin and Reid, 2004): the most unstable modes in parallel flows are two-dimensional.

A granular bed is not a continuum media, limiting the definition of small perturbations (undulations) on the bed surface and the employment of a continuum spectrum of normal modes (which are the basis of linear hydrodynamic stability analysis, Drazin and Reid (2004)). This limitation can be handled by supposing that the granular bed undulations need only to be smaller than some fluid flow scales (as the flow depth or the logarithmic layer of a turbulent boundary-layer, for example), as done by many authors (Kennedy, 1963; Engelund, 1970; Richards, 1980; Elbelrhiti et al., 2005 and Claudin and Andreotti, 2006). The same assumption is made here. To proceed with the analysis, the equations describing the problem are first presented.

Fluid Flow Perturbation

An undulation on a granular bed, such as a ripple or a dune, perturbs the fluid flow. The perturbation of a turbulent boundary-layer by a hill with small aspect ratio was analytically found by Jackson and Hunt (1975) and by Hunt et al. (1988). Their results were later applied to forms with higher aspect ratio by Weng et al. (1991). Jackson and Hunt (1975), Hunt et al. (1988) and Weng et al. (1991) found that the perturbed shear stress is shifted upstream the dune crest. Sauermann (2001) and Kroy et al. (2002) simplified the results of Weng et al. (1991) and obtained an expression containing only the dominant physical effects of this perturbation, making clear the reasons for this upstream shift. For a hill with a height h, a surface rugosity y_0 and a length 2L between the half-heights (total length $\approx 4L$), they showed that the perturbation of the longitudinal shear stress (dimensionless) is

$$\hat{\tau}_x = A \left(\frac{1}{\pi} \int \frac{\partial_x h}{x - \xi} d\xi + B \partial_x h \right) \tag{1}$$

where ξ is an integration variable and A and B are considered as constants, as they vary with the logarithm of L/y_0 (the variable used in the Jackson and Hunt (1975) gauge functions). Variations in three orders of magnitude of L/y_0 , $L/y_0 = 10^3$, $L/y_0 = 10^4$ and $L/y_0 = 10^5$, give A = 4.0, A = 3.6 and A = 3.3 and B = 0.63, B = 0.46 and B = 0.36, respectively. This means that changes in the length of the hill

(keeping the same rugosity) by three orders of magnitude have small effect in both A and B, which maintain the same order of magnitude. For a fixed bed, $y_0 = d/30$. For a moving bed, $y_0 \approx d$ in the case of gases and $y_0 \approx d/10$ in the case of liquids (Raudkivi, 1976).

The first term in the RHS of Eq. (1), the convolution product, is symmetric, similar to the potential solution of the flow perturbation by a hill. It comes from the pressure perturbations caused by the hill. The second term in the RHS of Eq. (1), which takes into account the local slope, is anti-symmetric. It comes from the non-linear inertial terms of the turbulent flow and can be seen as a second order correction of the potential solution, with minor changes in the magnitude of the first order solution, but causing an upstream shift. The perturbed fluid flow is then the unstable mechanism. The perturbation of a turbulent boundary-layer was experimentally measured by Sauermann et al. (2003) in the aeolian case and by Franklin (2008) in the aquatic case, and it agrees with Eq. (1). In the Fourier space, Eq. (1) may be written as (dimensionless)

$$\hat{\tau}_k = Ah(|k| + iBk) \tag{2}$$

where $k = \lambda^{-1}$ is the longitudinal wave-number (λ is the wavelength) and i is the imaginary number. If the perturbation is supposed small compared to a basic flow, the fluid flow over the bed can be written as a basic flow, unperturbed, plus a flow perturbation. For the shear stress on the bed surface

$$\tau = \tau_0 \left(1 + \hat{\tau} \right) \tag{3}$$

where τ_0 is the shear stress caused by the basic flow on the bed and $\hat{\tau}$ is the shear stress (without dimension) caused on the bed by the perturbation of the fluid flow. For a developed turbulent liquid flow over a granular bed, the basic flow is a rough turbulent boundary-layer, which has the well known logarithmic profile

$$u = \frac{u_*}{\kappa} log\left(\frac{y}{v_0}\right) \tag{4}$$

where κ is the Kármán constant, y_0 is the rugosity height, u(y) is the unperturbed velocity profile and u_* is the friction velocity, defined as $u_* = \tau_0^{1/2} \rho^{-1/2}$. The shear stress of the basic flow τ_0 is obtained from Eq. (4) and the perturbation $\hat{\tau}$ from Eq. (1) or (2).

Saturated Flow Rate of Grains

In a steady state regime, and without spatial variations, the fluid flow and the flow rate of grains are in equilibrium. The fluid flow entrains a certain amount of grains, which gets momentum from the fluid and dissipate it by shearing and by impacts with the fixed part of the granular bed. The fluid flow capability to transport grains is limited by this feed-back mechanism, and equilibrium is reached if there is enough length (or time) to the development of this interaction. The flow rate of grains in this equilibrium situation is known as "saturated flow rate of grains". Bagnold (1941) showed that, far from the incipient motion of grains,

$$q_{sat} \sim \tau^{\frac{3}{2}} \tag{5}$$

where q_{sat} is the volumetric flow rate of grains by unit of width. If the fluid flow perturbation is given by Eq. (3) (from Jackson and Hunt, 1975; Hunt et al. 1988 and Weng et al., 1991)

$$q_{sat} \sqrt{q_{sat}} \sim (1+\hat{\tau})^{3/2} \tag{6}$$

where Q_{sat} is the volumetric flow rate of grains by unit of width over a flat surface (basic state). A linear expansion can be made in Eq. (6), as suggested by Andreotti et al. (2002)

$$q_{sat} \sqrt{Q_{sat}} \sim 1 + \frac{3}{2} \left(Ah|k| + iBk \right) \tag{7}$$

Relaxation Effects

In the case of a fluid flow over an undulated bed, the shear stress caused by the fluid on the bed is always changing. The flow rate of grains will lag some distance (or time) with respect to the fluid flow, being then a stable mechanism. This distance is usually called "saturation length", L_{sat} .

A simplified expression taking into account this relaxation effect can be obtained from the erosion-deposition model of Charru et al. (2004):

$$\hat{\sigma}_x q = \frac{q_{sat} - q}{L_{sat}} \tag{8}$$

Equation (8), describing the relaxation of the flow rate of grains in varying fluid flow, is similar to the one obtained by dimensional considerations by Andreotti et al. (2002). A different equation was found by Sauermann et al. (2001), based on their continuum saltation model (not shown here).

Hersen et al. (2002), Andreotti et al. (2002), Kouakou and Lagrée (2005), Valance and Langlois (2005), Elbelrhiti et al. (2005) and Claudin and Andreotti (2006) consider that the saturation length has an inertial origin and is proportional to the traveling distance of individual grains, given by $L_{drag} = d \rho_p/\rho$, where ρ_p is the density of one grain. Parteli et al. (2007) found that, in the case of aeolian sand transport, $L_{sat} \sim L_{drag} u_*^{-2}$. In these expressions, L_{drag} is an inertial length-scale obtained when the density of the grain material is many times larger than the density of the fluid, $\rho_p >> \rho$. It is then pertinent when the fluid is a gas. When the fluid is a liquid, however, $\rho_p \approx \rho$ and it was argued by Charru (2006) and Franklin (2008) that this length-scale can no longer be applied. Instead, a relaxation length based on the deposition of an individual grain must be used, L_d :

$$L_{sat} \sim L_d = d \binom{u_*}{U_S} \tag{9}$$

Gravity Effects

Gravity weakens the transport of grains over positive slopes (upstream the crests) and facilitates it over negative slopes (downstream the crests), being inversely proportional to the slope of the bed. It is another stable mechanism. Gravity effects are felt by the flow rate of grains (which is proportional to the shear stress) and for this reason they are modeled here by computing an effective shear stress perturbation, even if weight and friction have different natures (the weight is a body force and the fluid friction is a surface force). This is a manner to take into account the effects of gravity without the need of an extra equation. The effective shear stress perturbation is given by.

$$\hat{\tau}_{eff,x} = A \left(\frac{1}{\pi} \int \frac{\partial_x h}{x - \xi} d\xi + B \partial_x h \right) - B_g \partial_x h \tag{10}$$

where B_g is a coefficient taking into account the weight of grains and the friction between them (it is different from B, from which comes turbulent terms and accounts for the fluid friction). Equation (10) can be written as

$$\hat{\tau}_{eff,x} = A \left(\frac{1}{\pi} \int \frac{\partial_x h}{x - \xi} d\xi + B_e \hat{\sigma}_x h \right)$$
 (11)

where $B_e = B - B_g/A$. The order of magnitude of B_g is 0.1 (Charru, 2006).

Mass Conservation

The two-dimensional mass conservation of grains is

$$\partial_t h + \partial_x q = 0 \tag{12}$$

This equation, known as *Exner equation*, links the height of the bed to the flow rate of grains.

Normal Modes and Solution

Given the small character of perturbations, the solutions of the preceding equations are plane waves. The bed height h and the flow rate of grains q can be decomposed in their normal modes

$$h(x,t) = H e^{\sigma t - i\omega t + ikx}$$
(13)

$$q(x,t)/Q_{sat} = 1 + Q e^{\sigma t - i\omega t + ikx}$$
(14)

where σ is the growth rate and ω is the frequency. Inserting Eqs. (13) and (14) into Eqs. (7), (8), (11) and (12), a 2 equation system is obtained

$$(\sigma - i\omega)H + ikQQ_{sat} = 0 (15)$$

$$(1+ikL_{sat})Q = \frac{3}{2}(A|k|+iB_ek)H$$
(16)

The growth rate σ and the frequency ω of initial instabilities are obtained from the non-trivial solution of the system of Eqs. (15) and (16)

$$\sigma = \frac{3Q_{sat}k^{2}(B_{e} - A|k|L_{sat})}{2(1 + (kL_{sat})^{2})}$$
(17)

$$\omega = \frac{3Q_{sat}k|k|(A + B_e|k|L_{sat})}{2(1 + (kL_{sat})^2)}$$
(18)

and the phase velocity $c=\omega/k$ of initial instabilities is

$$c = \frac{3Q_{sat}|k|(A + B_e|k|L_{sat})}{2(1 + (kL_{sat})^2)}$$
(19)

The most unstable (or amplified) mode is the one for which instabilities grow faster, corresponding to $\partial \sigma/\partial t = 0$. From Eq. (17)

$$3Q_{sat} \left| 2B_e k - AL_{sat} \left| k \left| k \left(3 + \left(kL_{sat} \right)^2 \right) \right| \right| = 0$$
 (20)

and, neglecting $(kL_{sat})^2$ (its order of magnitude is 0.1, as shown in Figs. 2, 3 and 4)

$$k_{max} \approx \frac{2B_e}{3A} \frac{1}{L_{cat}} \tag{21}$$

With the wave-number of the most unstable mode k_{max} , and noting that the orders of magnitude of A and B are respectively I and 0.1, the wavelength λ_{max} , the growth rate σ_{max} and the phase velocity c_{max} can be obtained for this mode:

$$\lambda_{max} \approx \frac{3A}{2B_o} L_{sat} \tag{22}$$

$$\sigma_{max} \approx \frac{2B^3}{9A^2} (A - 2)Q_{sat} \frac{1}{L_{sat}^2}$$
 (23)

$$c_{max} \approx \frac{B}{A} Q_{sat} \frac{1}{L_{sat}}$$
 (24)

Results From the Stability Analysis

Solutions of equations (17) and (19) can be computed with the known values of coefficients A and B. The values of B_g , d and u_* are directly linked to gravity effects, relaxation effects (considering Eq. (9)) and fluid flow, so that they will be used here as parameters to be varied. The variation of these parameters is able to show the influence of the three physical mechanisms on the wavelength, growth rate and celerity of the initial instabilities.

Examples of such solutions can be seen in Figs. 2, 3 and 4, using typical values of A = 4, B = 0.6 (typical for bed-forms under water, Franklin (2008)). The typical settling velocity of a grain U_S and the typical settling time $t_d = d/U_S$ are used in dimensionless variables.

$$U_S = \left[\frac{4}{3} \frac{1}{C_D} gd\left(\frac{\rho_p - \rho}{\rho}\right)\right]^{1/2} \tag{25}$$

The value of the drag coefficient C_D depends on the level of free stream turbulence and on the turbulence generated by the particle itself. In the case of a turbulent free stream, Raudkivi (1976) suggests the use of the classical Schiller-Neuman correlation (valid for $Re_S = U_S d/v < 80$)

$$C_D = \frac{24}{Re_S} \left(1 + 0.150 \, Re_S^{0.687} \right) \tag{26}$$

For grains with $d \approx 0.25$ mm and $\rho_p \approx 2500 \text{ kg/m}^3$ (corresponding to usual sand), Eqs. (25) and (26) show that the order of magnitude of U_S is 0.01 m/s.

Figures 2, 3 and 4 show the dimensionless growth rate σt_d and the dimensionless phase velocity c/U_S of the initial perturbations versus the dimensionless wave-number kL_{sat} . In these three figures, the continuous curves correspond to a baseline, where d=1 mm and $B_g=0$ (no gravity effect), and the dashed and dotted curves correspond to variations in the shear velocity u* (fluid flow effects), in grains diameter d (corresponding to the relaxation effects) and in the B_g coefficient (gravity effects), in Figs. 2, 3 and 4 respectively.

These figures show the existence of a cut-off wave-number, the small wave-numbers being always unstable and the long wave-numbers stable. This corresponds to long-wave instability. Also,

they show a preferential growth rate, allowing the prediction of the most unstable wavelength.

Figure 2 shows the effects of varying friction velocity u_* , the dashed curves corresponding to values of u_* equal to half of the values used in the continuous curves. Because U_S and d are the same in both cases, the saturation length varies as $L_{sat} \sim u_*$, which means that in the dashed curve L_{sat} is half of the value for the continuous curve. For the most unstable mode, Fig. 2 shows that a decrease in u_* by a factor 2 implies a decrease in the wavelength λ_{max} and in the growth rate σ_{max} by a factor 2, and a decrease in the phase velocity c_{max} by a factor 4.

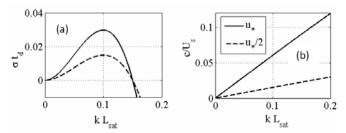


Figure 2. Dimensionless growth rate σt_d and dimensionless phase velocity c/U_S of the initial instabilities versus the dimensionless wave-number kL_{sat} in the case of fluid flow variation.

Those variations can be obtained from the simplified Eqs. (22), (23) and (24). As $L_{sat} \sim u_*$ and $Q_{sat} \sim u_*^3$ (Eq. (5)), one finds $\lambda_{max} \sim u_*$, $\sigma_{max} \sim u_*$, $c_{max} \sim u_*^2$. The scaling $\lambda_{max} \sim u_*$ is a consequence of the saturated length inserted in the model: $\lambda_{max} \sim L_d$. So, differently from previous stability analysis for turbulent regime, it is proposed here that the wavelength of the most unstable mode varies with the fluid flow as $\tau_0^{-1}/2$. The scaling $c_{max} \sim u_*^2$ agrees with the Bagnold (1941) expression for a dune displacement:

$$c_{dune} = \frac{Q_{sat}}{h_{dune}}$$
 (27)

where c_{dune} is the displacement velocity of a dune and h_{dune} is the dune height. With q_{sat} given by Eq. (5), $Q_{sat} \sim u_*^3$ and, as $H \sim L_{sat}$, one obtains $c_{dune} \sim u_*^2$, just as obtained for c_{max} .

The growth rate of the most unstable mode varies as $\sigma_{max} \sim u*$, as it should be expected from the physics of the problem. The shear stress caused by the fluid flow is the unstable mechanism, so the growth rate shall scale with the shear velocity divided by a typical length.

Figure 3 shows the effects of varying the grains diameter, dashed curves corresponding to values of grains diameter d equal to half of the values used in the continuous curves. This implies a variation of the saturation length L_{sat} with fixed fluid flow conditions. In order to simplify the analysis of the diagrams, the settling time t_d and the settling velocity U_S were kept constant. As the fluid flow is the same in the two cases, the saturation length varies as $L_{sat} \sim d$, so in the dashed curve L_{sat} is half of the value for the continuous curve. The variation $L_{sat} \sim d$, without changing the fluid flow conditions, can be seen as an isolation of the relaxation effects.

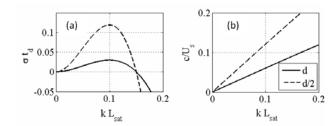


Figure 3. Dimensionless growth rate σt_d and dimensionless phase velocity c/U_S of the initial instabilities versus the dimensionless wave-number kL_{sat}, in the case of variation of grains diameter.

For the most unstable mode, Fig. 3 shows that a decrease in d by a factor 2 decreases the wavelength λ_{max} by a factor 2. Also, there is an increase in the growth rate σ_{max} by a factor 4 and an increase in the phase velocity c_{max} by a factor 2. As in the case of the fluid flow, those variations can be obtained from the simplified Eqs. (22), (23) and (24). As $L_{sat} \sim d$ (Eq. (9)), one finds $\lambda_{max} \sim d$, $\sigma_{max} \sim d^{-2}$, $c_{max} \sim d^{-1}$. Thus, the relaxation effects, present here in terms of grains diameter, have a stabilizing effect. In special, they stabilize the small waves and decrease the growth rate as $\sigma_{max} \sim L_{sat}^{-2}$. The scaling $c_{max} \sim L_{sat}^{-1}$ is a consequence of the Bagnold equation (Eq. (5)).

Figure 4 shows the effects of varying the coefficient B_g , the dashed curves corresponding to $B_g = 0.05$ and the dotted curves corresponding to $B_g = 0.1$. In this case, as the fluid flow and the grains diameter are kept constant, the saturation length L_{sat} is the same for all the three cases.

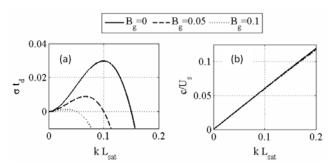


Figure 4. Dimensionless growth rate σt_d and dimensionless phase velocity c/U_S of the initial instabilities versus the dimensionless wave-number kL_{sat} , in the case of variations of B_g .

As seen in the preceding section, gravity effects were included in the perturbation of the shear stress, given by Eq. (11), via the coefficient B_g . This equation shows that gravity effects will be pronounced wherever the coefficient B_g of the anti-symmetric term varies strongly. This is the case for the growth rate: $\sigma_{max} \sim -B_g^3$, as can be seen from Eq. (23). Although gravity tends to stabilize small waves, Fig. 4 shows that its effects are much smaller than the relaxation and fluid flow ones. Gravity effects are mainly related to a strong decrease (as a power of 3 of B_g) in the growth rate.

Valance and Langlois (2005) obtained similar results, but for laminar shear flows. They found that the length-scale of the bedforms is given mainly by the relaxation effects if particle Reynolds number is relatively large ($Re_p = d^2 \tau / v_\mu > 100$), having the gravity

small influence on length-scale in this case. However, it is difficult to imagine laminar flow close to a granular bed with $Re_p > 100$,

with experiences showing that turbulence arises locally for Re_p around 5 (Bagnold, 1941).

In summary, the stability analysis showed the existence of long-wave instability, with the fluid flow conditions, the relaxation effects and the gravity effects playing an important role. It seems that the saturation length-scale L_{sat} , related to the relaxation effects, is the major responsible for the stabilization of small waves. It also plays a role in the growth rate, which varies as $\sigma_{max} \sim L_{sat}^{-2}$. On the other hand, gravity seems to play a smaller role in the stabilization of the small waves, but it strongly affects the growth rate. Changes in the fluid flow cause variations in the growth rate proportional to the shear velocity: $\sigma_{max} \sim u_*$. Concerning the wavelength of the most unstable mode, it scales with the fluid flow as $\lambda_{max} \sim u_*$. This is a result different from previous stability analysis for turbulent regime, where the wavelength of the most unstable mode was found to be unaffected by the fluid flow conditions.

Comparison to Experimental Data

Due to the technical difficulties in granular instability experiments, experimental uncertainties are very complex to be estimated and are not presented here. Instead, error-bars are presented whenever it is possible, corresponding to measurement deviations.

Kuru et al. (1995) presented a theoretical and experimental study of the initial instabilities on a granular bed on a horizontal pipe flow, which is a case without free-surface effects. Their experimental test section was a 31,1 mm diameter pipe, 7m long, and they employed a mixture of water and glycerin as the fluid media and glass beads as the granular media. More details can be found in Kuru et al. (1995). The theoretical work consisted of a linear stability analysis of a clear-layer (a layer containing only fluid) and a suspension-layer concurrent two-phase flow. They did not consider bed-load in their model, although the grains used and the fluid flow conditions are clearly in the bed-load range. They found that instabilities appear because the shear stresses caused by the clear-layer on the interface with the suspension-layer are shifted upstream to undulations on this interface. The wavelength found in their stability analysis overpredicts the experimental measurements, probably because they neglected bed-load transport and its relaxation effects.

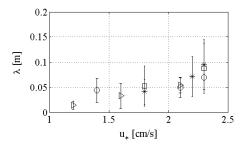


Figure 5. Mean wavelength λ of the initial instabilities versus the fluid shear velocity. Circles, asterisks, triangles and squares correspond to d = 0,3 mm and μ = 1 cP, d = 0,3 mm and μ = 2.2 cP, d = 0,1 mm and μ = 1 cP and d = 0,1 mm and μ = 2.1 cP, respectively. Error-bars correspond to deviations from the average value. Figure plotted with the data found in Kuru et al. (1995).

Their experimental results (performed mainly in turbulent regime) show that the initial wavelength scales with the flow rate of the carrier fluid (which indicates that the relaxation length is not of inertial nature in the case of liquids), as can be seen in Fig. 5. Their linear stability analysis was not able to explain the experimental results

Coleman et al. (2003) experimentally studied the granular bed instabilities in a closed-conduit turbulent liquid flow (without free-surface effects). Their experimental test section was a 6 m long horizontal closed-conduit of rectangular cross-section (300 mm wide by 100 mm high), and they employed water as the fluid media and glass beads as the granular media. The fluid flow was in the range 26000 < Re < 70000 (Re = UH/V), H is the channel height). More

details can be found in Coleman et al. (2003). They found that the initial instabilities have a well defined wavelength, which scales with the grains diameters but not with the fluid flow. They proposed the following expression for the initial wavelength (most unstable mode)

$$\lambda_{max} = 175d^{0,75} \tag{28}$$

In Eq. (28), there is no correlation between λ_{max} and the fluid flow, which indicates that the relaxation length would be of inertial nature. However, it should be noted that this equation has a dimensional inconsistency, λ_{max} being proportional to a diameter at a power 0.75 (so that the numerical constant has a dimension). It is then difficult to imagine Eq. (28) as a universal relation.

Franklin (2008) experimentally studied the initial instabilities on different granular beds under turbulent water flows. His experimental test section was a 6~m long horizontal closed-conduit of rectangular cross-section (120~mm wide by 60~mm high), made of transparent material. He employed water as the fluid media and glass and zirconium beads as the granular media. The fluid flow, in the range 13000 < Re < 24000, was measured by PIV (Particle Image Velocimetry), and the granular bed evolution was measured by a high definition camera. More details can be found in Franklin and Charru (2007), Franklin (2008) and Franklin and Charru (2009). Franklin's (2008) measurements showed that the initial bed-forms are two-dimensional, as predicted by the Squire's Theorem. After the initial two-dimensional phase, bed-forms evolve to three-dimensional forms, as seen in Fig. 6.

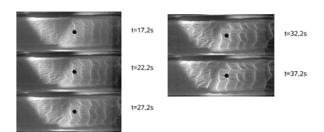


Figure 6. Evolution of the wavelength λ of initial ripples on a granular bed sheared by a turbulent water flow (top view). Flow direction is from right to left, Re = 19900 and the granular bed is composed of zirconium beads with d = 180 μ m. Figure extracted from Franklin (2008).

Figure 7(a) presents the mean wavelength λ of initial ripples as a function of the grains diameter d. In this figure, symbols correspond to mean values of experimental results, error-bars correspond to data dispersion and the line corresponds to Eq. (28), from Coleman et al. (2003). The mean values presented in Fig. 7(a) were computed for all grain types and water flow conditions. The tendency of Eq. (28) seems to agree with experimental data, but the numerical coefficient in Eq. (28) overestimates the wavelength. It was already noted that Eq. (28) has a dimensional inconsistency.

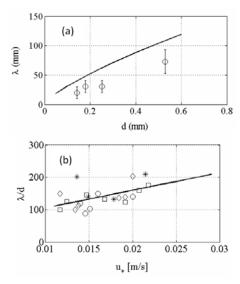


Figure 7. (a) Mean wavelength λ of the initial ripples as a function of grains diameter d. Symbols and error-bars correspond to experimental data and the line corresponds to Eq. (28). (b) Non-dimensional mean wavelength λ/d of initial ripples as a function of u. The lozenge, circle, square and asterisk symbols correspond d=0.12mm, d = 0.20 mm and d = 0.50 mm glass beads and to d = 0.19 mm zirconium beads, respectively. The line corresponds to a linear fit of the mean values. Figure plotted with the data from Franklin (2008).

Figure 7(b) presents the initial wavelengths normalized by the grains diameter λ/d as a function of the water flow shear velocity u*. This figure shows an increase of λ with the shear velocity, which indicates that the liquid flow conditions shall be taken into account: the deposition length L_d seems to be the correct length-scale.

From Figs. 5 and 7, the wavelength of the initial twodimensional ripples seems to vary with the liquid flow conditions, just as predicted by the stability analysis.

Conclusions

The transport of solid particles entrained by a fluid flow is frequent in nature and in industry. Under some fluid flow conditions, a mobile granular layer known as bed-load takes place, in which the grains stay in contact with the fixed part of the granular bed. In some situations, an initially flat granular bed may become unstable, giving rise to ripples or dunes. The formation of dunes in deserts and in petroleum pipelines conveying sand are some examples. A better knowledge of the instabilities on a granular bed and of their evolution is of great importance to understand nature.

This paper presented a theoretical investigation of the initial instabilities on granular beds sheared by turbulent liquid flows, without free-surface effects, such as those in which the liquid depth is many times greater than the typical height of the bed-forms, or flows in pipes and closed-conduits. The work consisted of a linear stability analysis of the problem, taking into consideration the fluid flow perturbation, the relaxation effects related to the flow rate of grains and the effects of gravity.

The stability analysis showed the existence of long-wave instability, whose behavior is influenced by fluid flow conditions, relaxation effects and gravity effects. The saturation length-scale L_{sat} , related to relaxation effects, seems to be the major responsible for the stabilization of small waves. It also affects the growth rate as $\sigma_{max} \sim L_{sat}^{-2}$. On the other hand, gravity seems to play a smaller role in the stabilization of the small waves, but it strongly affects the growth rate. The fluid flow was found to affect the growth rate as

 $\sigma_{max} \sim u_*$ and the celerity as $c_{max} \sim u_*^2$. It was also found to affect the wavelength, for which the following scaling is proposed: $\lambda_{max} \sim u_*$. This scaling is a result different from previous stability analysis for turbulent regime.

The results from the stability analysis were compared to some published experimental data concerning initial ripples in closedconduit flows, for liquids in turbulent regime. The works of Kuru et al. (1995) and Franklin (2008) showed that the wavelength of the initial ripples vary with the liquid flow conditions. These results agree with the stability analysis presented here.

In summary, differently from previous stability analysis for turbulent regime, it is proposed here that the initial wavelength varies with the flow conditions of the carrier liquid. This explains, for the first time, some previous experimental results.

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