

How to perform a coronary artery anastomosis in complete endoscopic fashion with robotic assistance

Como realizar anastomose coronariana totalmente endoscópica com assistência robótica

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Abstract

Current technology in robotic surgery allows us to perform myocardial revascularization procedures in a totally endoscopic fashion. We will describe the technique of choice for left internal mammary artery to left anterior descendent artery anastomosis with the use of cardiopulmonary bypass machine. The method is efficient and there is long term follow-up showing similar patency of the graft when compared to conventional methods (when performed through sternotomy).

Descriptors: Myocardial Revascularization. Surgical Procedures, Minimally Invasive. Thoracoscopy.

Totally endoscopic coronary artery bypass surgery with robotic assistance has become a feasible, safe and effective method for surgical coronary revascularization in selected patients^[1]. Either as an isolated therapy or as part of a hybrid approach the most common and main part of the procedure is the left internal mammary artery (LIMA) to left anterior descending artery (LAD) anastomosis. Different methods of endoscopic anastomosis have been described: running suture, use of nitinol clips and use of anastomotic connector device. Here we describe our technique of choice of running suture with Pronova 7-0.

The general conduct of operation has been extensively described elsewhere^[2] but can be summarized as follow. A dual lumen endotracheal tube is used to allow single right

Resumo

A tecnologia atual em cirurgia robótica permite realizar-se procedimento de revascularização do miocárdio de modo totalmente endoscópico. Descreveremos aqui a técnica de escolha para anastomose de artéria mamaria interna esquerda em artéria coronariana descendente anterior com uso de circulação extracorpórea. O método e eficaz e já existe acompanhamento a longo prazo mostrando patência do enxerto semelhante ao método convencional por esternotomia.

Descritores: Revascularização Miocárdica. Procedimentos Cirúrgicos Minimamente Invasivos. Toracoscopia.

lung ventilation. The patient cart of the robotic system approaches the patient from the right. The ports are placed on the left hemithorax with a deflated left lung: the camera port is inserted in the left fifth intercostal space in the anterior axillary line, the two robotic arm ports are inserted in the third and seven intercostal spaces, 3 cm anteriorly to the camera port. Lastly the myocardial stabilizer is inserted through a left subcostal port in the midclavicular line. The mammary takedown is performed with fine deBakey robotic forceps and a robotic electrocautery spatula using low energy (15W). A full description can be found elsewhere^[3].

While one surgeon is performing the LIMA harvesting, another one is preparing the left groin vessels for cardiopulmonary bypass (CPB) cannulation and insertion of an



Watch the video acessing the link below:

http://www.rbccv.org.br/video/2307/Como-realizar-anastomose-coronariana-totalmente-endoscopica-com-assistencia-robotica

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Abbreviations, acronyms & symbols	
СРВ	Cardiopulmonary bypass
LAD	Left anterior descending artery
LIMA	Left internal mammary artery

intra-aortic occlusive device. After the LIMA harvesting is complete, CPB is initiated, the pericardium is opened and the LAD target is identified. The intra-aortic occlusion device is inflated, and cardioplegia is delivered thorough its tip. Our cardioplegia solution of choice is Modified Buckberg. This is infused every 15 min, or earlier if there is electrical activity. When cardiac arrest is achieved our attention turns to the anastomosis confection. The coronary stabilizer is brought in and placed over the area of interest.

A proper spot for the anastomosis is chosen in the LAD based on quality of the artery wall and size of the vessel. The LIMA is checked for adequate flow and clamped with a bull-dog device. An endoscopic clip is placed in the adventitia of the mammary securing it to pericardial fat allowing it to be still. The mammary end is prepared by cutting it in a beveled fashion with endoscopic Pott scissors. The LAD is opened with an endoscopic scalpel (Figure 1) and the arteriotomy is increased with Pott scissors to a size of 4 mm.

If considerable backflow from the perforators compromise view, proximal and distal snare of the artery are possible with vessel loops. The mammary artery is positioned close to the opened coronary artery. For the anastomosis confection two delicate Black Diamonds forceps are used. The stitch used is a 7-0 Pronova, 7 cm long with small needle. The first stitch goes from inside to the outside of the coronary close to the toe of the anastomosis, in the back wall. The needle is pulled and parked in the myocardial fat. The other needle takes a bite inside-out in the mammary artery at the distal back wall (Figure 2).

The next three stitches will enter the coronary artery from the outside and the mammary artery in a parachute mode,



Fig. 1 - Opening of coronary artery (LAD) with endoscopic scalpel.

travelling proximally. The mammary artery is then brought down. The suture continues proximally with the needle being handled in a right hand fashion. Adjustment of the line of suture is possible using the needle. When the heel is reached, extra care should be taken to avoid suturing the posterior wall, which would lead to obstruction of the anastomosis. The Black Diamond forceps can be used to kindly test for patency. When the heel is passed, the running suture continues, but the needle is handled in a left hand fashion (Figure 3).

This continues up to the middle of the front wall. At this point this needle is parked and the first one is taken again. The suture then comes from distal to proximal, including the toe of the anastomosis (Figure 4). Again, this can be tested for patency with the fine Black Diamond forceps. When the two sutures meet in the middle of the anterior wall, the needles are removed by breaking the stitch and they are used to put tension on the whole suture line. This is an important step since this procedure is performed in a solo fashion, without an assistant keeping tension on the suture during its confection.

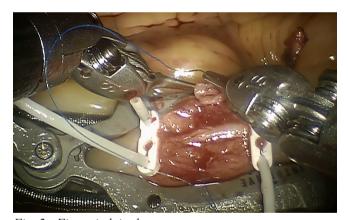


Fig. 2 - First stitch in the mammary artery.

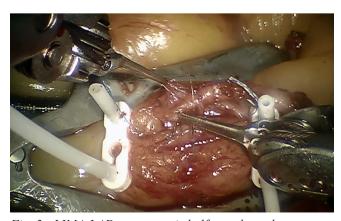


Fig. 3 - LIMA-LAD anastomosis half way through.

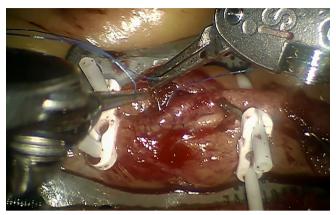


Fig. 4 - Last stitch in LIMA-LAD anastomosis.

The suture is then tied down with several knots. The mammary artery is opened to test for any bleeding and repair stitches are placed as necessary (Video 1).

After the anastomosis is complete, the endo-ballon is deflated and the heart starts to beat. An ultrasound probe is brought into the cavity through the left subcostal port and applied to the mammary artery to access for flow. Further hemostasis of the anastomosis and mammary artery bed are performed.

The patency of robotic totally endoscopic LIMA-LAD anastomosis has been found to be similar to conventional open procedures^[1,4,5]. Angiographic and coronary CT studies have found this patency to be between 92%^[4] and 98%^[5] on the long term. The average time to perform the anastomosis has been reported in several studies to be between 18 and 35 minutes^[6].

In many situations the revascularization approach follows a hybrid philosophy. In this case one or two IMAs are anastomosed to arteries of the left ventricle with robotic assistance and percutaneous intervention with stents are performed to the remaining vessels. The order of the procedures can vary and depends on clinical status, risk of bleeding and severity of coronary lesions.

We here describe our technique of choice for robotic LI-MA-LAD anastomosis. Pictures and video further illustrates the procedure.

Authors' roles & responsibilities	
LSC	Final approval of the manuscript conception and study design, performed procedures, and/or experiments, writing of the manuscript or review of its content
JВ	Final approval of manuscript conception and study design, performed procedures, and/or experiments, writing of the manuscript or review of its content

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