HIGHLY-ACCURATE MODEL ORDER REDUCTION TECHNIQUE ON A DISCRETE DOMAIN


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Abstract - In this work, we present a highly-accurate technique of model order reduction applied to staged processes. The proposed method reduces the dimension of the original system based on null values of moment-weighted sums of heat and mass balance residuals on real stages. To compute these sums of weighted residuals, a discrete form of Gauss-Lobatto quadrature was developed, allowing a high degree of accuracy in these calculations. The locations where the residuals are cancelled vary with time and operating conditions, characterizing a desirable adaptive nature of this technique. Balances related to upstream and downstream devices (such as condenser, reboiler, and feed tray of a distillation column) are considered as boundary conditions of the corresponding difference-differential equations system. The chosen number of moments is the dimension of the reduced model being much lower than the dimension of the complete model and does not depend on the size of the original model. Scaling of the discrete independent variable related with the stages was crucial for the computational implementation of the proposed method, avoiding accumulation of round-off errors present even in low-degree polynomial approximations in the original discrete variable. Dynamical simulations of distillation columns were carried out to check the performance of the proposed model order reduction technique. The obtained results show the superiority of the proposed procedure in comparison with the orthogonal collocation method.

Keywords: Model order reduction; Discrete domain; Weighted residuals; Orthogonal collocation; Method of moments; Distillation column.

INTRODUCTION

Rigorous dynamic mathematical models of staged separation systems with mass and energy balances lead to a large set of differential-algebraic equations, making them impractical for real-time applications. The challenge to reduce the computational cost of such systems motivated the development of different model order reduction techniques, such as compartmental models (España and Landau, 1978; Benalloul et al., 1986; Musch and Steiner, 1993) and its variants aggregated modeling (Lévine and Routhing, 1991; Linhart and Skogestad, 2009, 2010; Kamath et al., 2011) and time-scale separation (Kumar and Daoutidis, 2003) based on singular perturbation analysis, nonlinear wave propagation (Marquardt, 1986; Kienle, 2000), model linearization (Georgakis and Stoever, 1982), and orthogonal collocation.

The orthogonal collocation technique for solving boundary value problems described by differential equations on continuous domains is well developed since the works of Villadsen and Stewart (1967), Finlayson (1972) and Villadsen and Michelsen (1978), and revisited in Lemos et al. (2014). Wong and Luus (1980) were the first to apply orthogonal collocation for order reduction of staged separation systems, by transforming the difference-differential equations into partial differential equations with
subsequent application of the orthogonal collocation method in a continuous domain. Also in continuous domain, Kim et al. (2010) applied orthogonal collocation on finite elements using the temperature as independent variable and showed the advantage of this transformation for rigorous separation design. Cho and Joseph (1983) showed that it is possible to apply the orthogonal collocation method directly in the discrete domain by adequate selection of polynomials. Stewart et al. (1985) further showed that Hahn’s polynomials are the best choice for better results and more reliable reduced models. Following this approach, Pinto and Biscaia (1987) presented four different order reduction strategies dealing with the discontinuities that happen between the sections of staged separation systems, whereas Seferlis and Hrymak (1994) treated all discontinuous stages as discrete stages and applied order reduction for each section between these discrete stages using the orthogonal collocation on finite elements technique with different polynomials for the vapor and liquid phases.

In this work we present a technique of model order reduction of staged separation systems based on null values of moment-weighted sums of heat and mass balance residuals on real stages, referred here as method of moments, for short. In order to compute these sums of weighted residuals, a discrete form of Gauss-Lobatto quadrature was developed, allowing a high degree of accuracy in these calculations. Mass and energy balances related to upstream and downstream devices (such as condenser, reboiler, and feed tray of a distillation column) are considered as boundary conditions of the corresponding difference-differential equations system, and by also defining residual functions for the boundary points, representing fictitious stages, we deal with the discontinuities that may occur at these points using only one polynomial for each section. Using illustrative examples, we also show the adaptive nature of the proposed technique, where the locations of the null residuals of the model equations vary with time and the operating conditions. Scaling of the discrete independent variable related with the stages is also introduced in this work, which has been a drawback for applying discrete orthogonal collocation methods, avoiding accumulation of round-off errors present even in low-degree polynomial approximations in the original discrete variable.

In the next section we present the method of moments in a general form to be applied to any staged process. Also in this section, a change in the independent variable was applied to increase the stability of the numerical procedure. Then, the methodology is applied in detail to a simple absorber column in order to present all steps of the procedure and we also applied the method of moments to binary and ternary distillation columns to show the advantages of this approach when compared with the orthogonal collocation method.

ORDER REDUCTION TECHNIQUE

In order to introduce the proposed model order reduction technique, let us consider a generic section of an N-stage system described by the following difference-differential equations:

\[ \frac{d\hat{x}_i(t)}{dt} = f(\hat{x}_{i-1}(t)) + g(\hat{x}_i(t)) + h(\hat{x}_{i+1}(t)), \]

\[ i = 1, 2, ..., N \]

with boundary conditions \( \hat{x}_0(t) = \rho(t) \) and \( \hat{x}_{N+1}(t) = q(t) \) with known functions \( \rho(t) \) and \( q(t) \); \( f(\cdot) \), \( g(\cdot) \), and \( h(\cdot) \) are functions resulting from the application of mass and/or energy conservation laws, and \( \hat{x}_i(t) \) represents the system state variables, e.g., mole fraction or temperature of the \( i \)-th stage. Using the following scaled independent variable representing the stages of the system:

\[ s_i = \frac{i-1}{N}, \quad i = 1, 2, ..., N \]

and the notation \( \hat{x}(s_i, t) = \hat{x}_i(t) \), then a polynomial approximation of degree \( n + 1 \) in the state variables \( \hat{x}_i(t) \), considering the internal points \( 0 \leq s^{(1)} < s^{(2)} < \ldots < s^{(n)} < 1 \) and the extreme points \( s^{(0)} = -1/N \) at \( i = 0 \) and \( s^{(n+1)} = 1 \) at \( i = N + 1 \) as interpolation points, can be written as:

\[ \hat{x}(s, t) \approx x^{(n+1)}(s, t) = \sum_{j=0}^{n+1} \ell_j(s) \hat{x}(s^{(j)}, t) = \sum_{j=0}^{n+1} \ell_j(s) x_j(t) \]  \( (3) \)

where \( \ell_j(s) = \prod_{k=0, k \neq j}^{n+1} \frac{(s-s_k)}{(s_j-s_k)} \) are the Lagrange interpolating polynomials and, for sake of notation, \( x_j(t) = \hat{x}(s^{(j)}, t) \). Note that in the limiting case of \( n = N \), the internal interpolating points are equal to the system stages, \( s^{(i)} = s_i \) for \( i = 1, 2, ..., N \), and the reduced model is equivalent to the complete model, i.e., \( x_i(t) = \hat{x}_i(t) \).
For each interpolating point, \( i = 0, 1, 2, \ldots, n + 1 \), the following residual functions are defined:

\[
\mathcal{R}^{(n+1)}(s^{(i)},t) = \frac{dx_i(t)}{dt} - f[s^{(n+1)}(s^{(i)} - 1/N, t)] - g[x_i(t)] - h[s^{(n+1)}(s^{(i)} + 1/N, t)]
\]

(4)

where the first-order negative and positive differences are evaluated as:

\[
f[s^{(n+1)}(s^{(i)} - 1/N, t)] = \sum_{j=0}^{n+1} \ell_j(s^{(i)} - 1/N) f[x_j(t)]
\]

(5)

\[
h[s^{(n+1)}(s^{(i)} + 1/N, t)] = \sum_{j=0}^{n+1} \ell_j(s^{(i)} + 1/N) h[x_j(t)]
\]

(6)

where \( A_{ij} = \ell_j(s^{(i)} - 1/N) \) and \( A_{ij}^+ = \ell_j(s^{(i)} + 1/N) \) are the \((n + 2) \times (n + 2)\) first-order difference matrices. Note that in Eq. (4) the residual function is also defined for the boundary points, representing fictitious stages to deal with discontinuities that may occur at the boundaries, which are used by the method of moments and discussed later.

In the classical method of discrete orthogonal collocation, \( x_i(t) \) are found such that the residuals at the internal points, \( i = 1, 2, \ldots, n \), are canceled (collocation points):

\[
\mathcal{R}^{(n+1)}(s^{(i)},t) = 0 = \frac{dx_i(t)}{dt} - \sum_{j=0}^{n+1} A_{ij}^- f[x_j(t)] - g[x_i(t)] - \sum_{j=0}^{n+1} A_{ij}^+ h[x_j(t)]
\]

(7)

and the boundary conditions \( x_0(t) = p(t) \) and \( x_{n+1}(t) = q(t) \) complete the system of \( n + 2 \) equations.

In order to avoid the discontinuities that may occur at the boundaries, an approach similar to Seferlis and Hrymak (1994) can be applied in the classical method by adding two extra collocation points at the extreme stages of the section of the separation system, at \( s^{(0)} = 0 \) and at \( s^{(n+1)} = 1 - \frac{1}{N} \), corresponding to the stages 1 and \( N \), respectively, and for these points the residuals are defined as:

\[
\mathcal{R}^{(n+1)}(s^{(0)},t) = 0 = \frac{dx_0(t)}{dt} - f[x_1(t)] - g[x_0(t)] - \sum_{j=0}^{n+1} A_{0j}^+ h[x_j(t)]
\]

(8)

\[
\mathcal{R}^{(n+1)}(s^{(n+1)},t) = 0 = \frac{dx_{n+1}(t)}{dt} - \sum_{j=0}^{n+1} A_{n+1,j}^- f[x_j(t)] - g[x_{n+2}(t)] - h[x_{n+1}(t)]
\]

(9)

where the boundary conditions are \( x_i(t) = p(t) \) and \( x_{n+2}(t) = q(t) \). However, this modified approach has the disadvantage of increasing the size of the system by adding two extra collocation points, or reducing the degree of the orthogonal collocation polynomial by two if keeping the same size of the classical method.

In the method of moments, \( x_i(t) \) are found such that sum of the moment-weighted residuals is canceled for the first \( n \) moments:

\[
\mathcal{R}_k^{(n+1)}(s^{(i)},t) = \sum_{i=1}^{N} (s_i)^{k-1} \mathcal{R}^{(n+1)}(s_i,t) = 0,
\]

(10)

\( k = 1, 2, \ldots, n \)

These sums of weighted residuals are evaluated using a discrete form of Gauss-Lobatto quadrature:

\[
\mathcal{R}_k^{(n+1)}(t) = \sum_{j=0}^{n+1} \omega_j (s^{(j)})^{k-1} \mathcal{R}^{(n+1)}(s^{(j)},t) = \sum_{j=0}^{n+1} M_{kj} \mathcal{R}^{(n+1)}(s^{(j)},t) = 0
\]

(11)

\( k = 1, 2, \ldots, n \)

where \( M_{kj} = \omega_j (s^{(j)})^{k-1} \) are the entries of the \( n \times (n + 2) \) matrix \( M \) and \( \omega_j \) and \( s^{(j)} \) are the weights and abscissas of the Gauss-Lobatto quadrature, respectively. This quadrature is exact for polynomial functions up to degree \( 2n + 1 \), which is always the case for linear systems because \( \mathcal{R}^{(n+1)}(s,t) \) is a polynomial of degree \( n+1 \).

As the \( n \) equations in Eq. (11) are linear in the coefficients of matrix \( M \), they can be rewritten in the following form:

\[
\mathcal{R}^{(n+1)}(s^{(i)},t) + V_{i0} \mathcal{R}^{(n+1)}(s^{(0)},t) + V_{i1} \mathcal{R}^{(n+1)}(s^{(n+1)},t) = 0, \quad i = 1, 2, \ldots, n
\]

(12)
where \([V_0, V_1] = \mathbf{M}^{-1}[b_0, b_1]\), \(b_{i,0} = M_{i,0}\) are the entries of the first column of matrix \(\mathbf{M}\), \(b_{i,1} = M_{i,0+1}\) are the entries of the last column of matrix \(\mathbf{M}\), and \(\mathbf{M}\) is the \(n \times n\) square matrix by removing the first and the last columns of matrix \(\mathbf{M}\). By substituting Eq. (4) in Eq. (12), the following expression can be derived:

\[
\frac{dX_i(t)}{dt} = \sum_{j=0}^{n+1} B_{i,j} f[x_j(t)] + G[x_i(t)] + \sum_{j=0}^{n+1} B_{i,j} h[x_j(t)] \quad i = 1, 2, \ldots, n
\]

where \(X_i(t) = x_i(t) + V_{i,0} x_0(t) + V_{i,1} x_{n+1}(t)\),

\[
B_{i,j} = A_{i,j} + V_{i,0} A_{i,0} + V_{i,1} A_{i,n+1,j},
\]

\[
B_{i,j} = A_{i,j} + V_{i,0} A_{i,0} + V_{i,1} A_{i,n+1,j}, \quad \text{and}
\]

\[
G[x_i(t)] = g[x_i(t)] + V_{i,0} g[x_0(t)] + V_{i,1} g[x_{n+1}(t)].
\]

The boundary conditions \(x_0(t) = p(t)\) and \(x_{n+1}(t) = q(t)\) complete the system of \(n + 2\) equations. Note that the orthogonal collocation technique is reproduced by setting \(V_{i,0} = 0\) and \(V_{i,1} = 0\). In both cases, \(s^{(1)}, s^{(2)}, \ldots, s^{(n)}\) are the roots of the Hahn’s polynomial of degree \(n\).

Figure 1 shows that the roots of the Hahn’s polynomial are obtained with high accuracy for any degree when using the proposed scaled discrete independent variable, whereas high accumulation of round-off errors is observed in the original discrete variable, even for low-degree polynomials.

**RESULTS AND DISCUSSION**

Four separation processes were chosen to illustrate the methodology and to show its advantages when compared with the classical orthogonal collocation method: (1) a simple absorber column, to present all steps of the procedure; (2) a high-purity propane-propylene distillation column with large number of stages, to show the high reduction of the model order; (3) a benzene-toluene-xylene distillation column, to apply the method to a multicomponent system and to show its high accuracy close to the boundaries of the distillation sections; and (4) an ethanol-propanol-water distillation column, to show the performance of the method for non-ideal mixtures.

All differential-algebraic systems presented in this section were solved by the solver DASSLC (Secchi, 2009) with relative accuracy of \(10^{-6}\) and absolute accuracy of \(10^{-8}\), implemented in the dynamic simulator EMSO (Soares and Secchi, 2003).

**Absorber Column**

This simple hypothetical example of an absorber column demonstrates the application of the method of moments for model order reduction of a staged separation system described by the following difference-differential equations:

\[
\frac{d\hat{x}_i(t)}{dt} = \beta \hat{x}_{i-1}(t) - \left[\beta \hat{\hat{x}}_i(t) + \hat{y}_i(t)\right] + \hat{y}_{i+1}(t),
\]

\(i = 1, 2, \ldots, N\)

and thermodynamic equilibrium:

\[
\hat{y}_i(t) = y_{eq}[\hat{x}_i(t)] = \frac{\alpha \hat{x}_i(t)}{1 + (\alpha - 1) \hat{x}_i(t)},
\]

\(i = 0, 1, 2, \ldots, N + 1\)

with the boundary conditions:

\[
\hat{x}_0(t) = x_{feed}(t)
\]

\(\hat{y}_{N+1}(t) = y_{feed}(t)\)
where $\alpha$ (relative volatility) and $\beta$ (liquid/gas molar flow ratio) are model parameters, and $t$ is the dimensionless time (actual time multiplied by the ratio of the gas molar flow rate and molar holdup). Writing Eq. (14) in the form of Eq. (1) results in

$$\frac{dX_i(t)}{dt} = \beta \sum_{j=0}^{n+1} B_{ij}^- x_j(t) - \left(\beta X_i(t) + Y_i(t)\right)$$

$$+ \sum_{j=0}^{n+1} B_{ij}^+ y_j(t), \quad i = 1, \ldots, n$$

where

$$X_i(t) = x_i(t) + V_{i,0} x_0(t) + V_{i,1} x_{i+1}(t),$$

$$Y_i(t) = y_i(t) + V_{i,0} y_0(t) + V_{i,1} y_{i+1}(t),$$

and

$$y_i(t) = y_{eq}[x_i(t)].$$

The reduced model by the orthogonal collocation method (OC), given by Eq. (7), is written as:

$$\frac{dX_i(t)}{dt} = \beta \sum_{j=0}^{n+1} A_{ij}^- x_j(t) - \left(\beta X_i(t) + Y_i(t)\right)$$

$$+ \sum_{j=0}^{n+1} A_{ij}^+ y_j(t), \quad i = 1, \ldots, n$$

In both cases, $x_0(t) = x_{feed}(t)$ and $y_{n+1}(t) = y_{feed}(t)$.

Using a set of arbitrary specifications given in Table 1, the corresponding results are shown in Figure 2, where both reduced order techniques present good agreement with the complete model for a reduction of 83%. The method of moments shows slightly better results in the regions near to the column top and bottom, with less oscillatory behavior, as show in Table 2 for the first two stages at the top and bottom of the column. These characteristics are better explored in the next and more realistic examples.

### Table 1: Absorber column specifications.

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of internal points, $n$</td>
<td>5</td>
</tr>
<tr>
<td>Number of stages, $N$</td>
<td>30</td>
</tr>
<tr>
<td>$\beta$</td>
<td>1.0</td>
</tr>
<tr>
<td>$\alpha$</td>
<td>0.75</td>
</tr>
<tr>
<td>$x_{feed}$</td>
<td>0.0</td>
</tr>
<tr>
<td>$y_{feed}$</td>
<td>1.0</td>
</tr>
</tbody>
</table>

### Distillation Column – Propane and Propylene

In order to compare the method of moments with the orthogonal collocation method, a distillation column to separate propane and propylene was used, as described in Seferlis and Hrymak (1994), with the specifications given in Table 3. The main characteristic of this example is the large number of stages, which is appropriate to show the high-degree of reduction that can be achieved by these methods.

### Table 3: Distillation column specifications for the propylene–propane system.

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of trays</td>
<td>175</td>
</tr>
<tr>
<td>Feed tray</td>
<td>116</td>
</tr>
<tr>
<td>Feed composition (propylene, propane)</td>
<td>[0.8973 0.1027]</td>
</tr>
<tr>
<td>Feed flow rate (kmol/d)</td>
<td>1073.4</td>
</tr>
<tr>
<td>Feed temperature (K)</td>
<td>46.11</td>
</tr>
<tr>
<td>Operating pressure (kPa)</td>
<td>1860.6</td>
</tr>
<tr>
<td>Reflux ratio</td>
<td>19.7</td>
</tr>
<tr>
<td>Distillate flow rate (kmol/d)</td>
<td>965</td>
</tr>
<tr>
<td>Condenser vapour flow rate (kmol/d)</td>
<td>0</td>
</tr>
<tr>
<td>Condenser molar holdup (kmol)</td>
<td>20</td>
</tr>
<tr>
<td>Trays molar holdup (kmol)</td>
<td>0.4</td>
</tr>
<tr>
<td>Reboiler molar holdup (kmol)</td>
<td>25</td>
</tr>
</tbody>
</table>

The Peng-Robinson equation of state was used for evaluation of the thermodynamic properties in both liquid and vapor phases. In the reduced models, 5 internal points were used in the rectifying section, and only 3 points in the stripping section, i.e., a re-
duction of 95%. In Figures 3 to 6, the steady-state profiles of liquid mole fraction, temperature and errors between the complete model and the reduced models using the method of moments and the orthogonal collocation method are presented, respectively, where the superiority of the method of moments in comparison with the orthogonal collocation method can be observed for the downstream variables, mainly at the bottom of the column. These results are better visualized in Table 4, where the absolute square errors relative to the complete model are given for (1) sum of these errors over all stages, (2) maximum error, (3) condenser error, (4) reboiler error, and (5) feed tray. The errors of the orthogonal collocation method at the bottom and top stages are about three times larger than the method of moments for both composition and temperature, which is an important advantage for control applications, such as the dual composition control of a high-purity distillation column.

In order to illustrate the dynamic behavior, a step function of 12% was applied in the reflux ratio at 0.4 h changing from 19.7 to 22, starting the simulation at the steady-state condition. In Figure 7, the step response of the propylene composition and the temperature in the distillate are presented, showing the predictive capacity of the 95% reduced model even for the transient behavior.

### Table 4: Absolute square errors relative to the complete model for the liquid composition and temperature in the propane-propylene column:

<table>
<thead>
<tr>
<th>Errors</th>
<th>Mole Fraction</th>
<th>Temperature</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Moments OC</td>
<td>Moments OC</td>
</tr>
<tr>
<td>Sum</td>
<td>2.92937</td>
<td>3.46050</td>
</tr>
<tr>
<td>Max</td>
<td>0.02358</td>
<td>0.03273</td>
</tr>
<tr>
<td>Top</td>
<td>0.00055</td>
<td>0.00155</td>
</tr>
<tr>
<td>Bottom</td>
<td>0.00487</td>
<td>0.01379</td>
</tr>
<tr>
<td>Feed</td>
<td>0.00590</td>
<td>0.01721</td>
</tr>
<tr>
<td></td>
<td>12.172</td>
<td>14.787</td>
</tr>
<tr>
<td></td>
<td>0.202</td>
<td>0.283</td>
</tr>
<tr>
<td></td>
<td>0.004</td>
<td>0.012</td>
</tr>
<tr>
<td></td>
<td>0.043</td>
<td>0.122</td>
</tr>
<tr>
<td></td>
<td>0.025</td>
<td>0.028</td>
</tr>
</tbody>
</table>

### Figure 5: Steady-state temperature profiles for the complete model, method of moments, and orthogonal collocation of the propane-propylene column.

### Figure 6: Steady-state temperature error profiles for the method of moments and the orthogonal collocation of the propane-propylene column, highlighting the better accuracy of the moments close to the boundaries.
highly-accurate model order reduction technique on a discrete domain

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Figure 7: Distillate temperature and composition response due to a +12% step change in the reflux ratio at 0.4 h for the complete and reduced models of the propane-propylene column.

The adaptive nature of the method of moments is demonstrated by showing the moving collocation points, i.e., the points where the residuals are null, compared with the fixed points of the orthogonal collocation method. In Figures 8 and 9, the residual function of the propylene mass balance in the rectifying section, at three different time points, is depicted for the method of moments and orthogonal collocation methods, respectively.

Figures 10 and 11 present the propylene composition profiles and the distribution of errors calculated by the difference between the composition from the method of moments and the composition from the complete model at different times. These results were generated with 88% reduction in the model order by using 3 internal points in the rectifying section and 3 points in the stripping section, using the data of Table 3, except for the number of trays that was set to 49 and the feed tray location that was set to 25, and applying the same step change as described in the previous paragraph. A smaller column was used in this example to have a better approximation of both reduced models, when compared with the complete model, and to focus the analysis on the location of the collocation points. The three time points were chosen to be located near to the initial and final steady-states (t = 0.1 h and t = 14.9 h) and after the step change (t = 0.4 h). The movement of the collocation points in the method of moments during the transient can be observed in Figure 8 after the step change in the reflux ratio, and the return of these points close to the location of the initial steady-state when the column reached the new steady-state. This behaviour may be explained by the step response of the propylene composition, Figure 12, which presents an overshoot after the step change, and then moves back to a steady-state near to the initial condition. Figure 9 shows the fixed collocation points of the orthogonal collocation method, which does not present the desired adaptability to changes in the operating conditions that may cause significant changes in the profile shape, requiring the relocation of the collocation points to maintain the approximation accuracy. In Table 5, the exact locations of the collocation points are given as function of the time.
Figure 10: Propylene composition in the rectifying section for the complete and moments models at times 0.1 h and 14.9 h.

Figure 11: Propylene composition error of the method of moments in the rectifying section at times 0.1 h and 14.9 h.

Figure 12: Propylene composition response due to a +12% step change in the reflux ratio at 0.4 h for the method of moments for the column with 51 stages.

Table 5: Location of the collocation points as a function of the time.

<table>
<thead>
<tr>
<th>time</th>
<th>root 1</th>
<th>root 2</th>
<th>root 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1</td>
<td>4.233</td>
<td>13.75</td>
<td>22.60</td>
</tr>
<tr>
<td>0.4</td>
<td>6.556</td>
<td>15.65</td>
<td>23.32</td>
</tr>
<tr>
<td>0.6</td>
<td>3.069</td>
<td>8.867</td>
<td>17.63</td>
</tr>
<tr>
<td>0.8</td>
<td>5.750</td>
<td>15.33</td>
<td>23.11</td>
</tr>
<tr>
<td>1.0</td>
<td>4.783</td>
<td>14.47</td>
<td>22.96</td>
</tr>
<tr>
<td>1.6</td>
<td>4.350</td>
<td>13.30</td>
<td>22.88</td>
</tr>
<tr>
<td>2.0</td>
<td>4.227</td>
<td>13.42</td>
<td>22.55</td>
</tr>
<tr>
<td>14.9</td>
<td>4.222</td>
<td>13.67</td>
<td>22.98</td>
</tr>
</tbody>
</table>

Table 6: Distillation column specifications for the benzene–toluene–o-xylene system.

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of trays</td>
<td>20</td>
<td></td>
</tr>
<tr>
<td>Feed tray</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>Feed composition (benzene, toluene, o-xylene)</td>
<td>[0.15 0.25 0.60]</td>
<td></td>
</tr>
<tr>
<td>Feed flow rate (kmol/d)</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>Feed temperature (K)</td>
<td>410</td>
<td></td>
</tr>
<tr>
<td>Operating pressure (kPa)</td>
<td>200</td>
<td></td>
</tr>
<tr>
<td>Reflux ratio</td>
<td>5</td>
<td></td>
</tr>
<tr>
<td>Distillate flow rate (kmol/d)</td>
<td>50</td>
<td></td>
</tr>
</tbody>
</table>

Distillation Column – Benzene, Toluene and o-Xylene

In order to show that these methods of reduced order are not limited to binary systems, the third example is a distillation column to separate a ternary mixture of benzene, toluene and o-xylene (BTX) as applied by Pinto and Biscaia (1987) and Kamath et al. (2010), with the specifications given in Table 6. The Peng-Robinson equation of state was used in the vapor phase and the UNIFAC model was used in the liquid phase to evaluate the thermodynamic properties.

Figure 13 illustrates the effects of the order reduction on the accuracy of the method of moments to reproduce the composition and temperature profiles of the complete model. Both order reduction methods
have been successful to reproduce the complete model using 4 internal points in each section. However, when the main focus is to obtain the highest possible reduction with good accuracy to reproduce the conditions at the top and bottom of the column, as in the case of control strategies of a distillation column, the method of moments has great advantage as shown in the results for only two internal points in each section.

**Figure 13:** Steady-state benzene composition and temperature profiles for the method of moments for different order reductions.

In Figure 14 to 16, the steady-state profiles of liquid mole fraction of benzene, temperature and errors between the complete model and the reduced models using the method of moments and the orthogonal collocation method are presented, respectively. In the reduced models, 2 internal points were used in both the rectifying and stripping sections, i.e., a reduction of 80%. In this example, the superiority of the method of moments is more evident. These results are also visualized in Table 7, with the same definitions used in the previous example.

**Figure 14:** Steady-state benzene composition and temperature profiles for the complete model, method of moments, and orthogonal collocation of the BTX column.

**Figure 15:** Steady-state benzene composition error profiles for the method of moments and the orthogonal collocation of the BTX column.

**Figure 16:** Steady-state temperature error profiles for the method of moments and the orthogonal collocation of the BTX column.

The oscillatory behavior observed in Figure 14 is due to the use of an interpolation polynomial, Eq. (3), to rebuild the complete profile in the real stages. If only the calculated points were plotted this oscillatory behavior would not appear. Local interpolation formulas (like splines) could be used to mitigate this behavior. However, this interpolation was applied solely for visualization purposes, because when using reduced models only the reduced stages are necessary.
The errors of the orthogonal collocation method at the feed tray are about five times larger than the method of moments and at the top of the column are about two orders of magnitude larger than the method of moments for both composition and temperature, which is an important advantage of the method of moments for control and other real time applications. The lower sum of the absolute square errors (Sum) and maximum absolute square errors (Max) of the method of moments also indicate the overall high performance of this method compared with the orthogonal collocation method. It only presents a slightly higher error at the bottom of the column for the composition and a more significant error in the feed tray temperature, but representing less than 0.08% of the bottom temperature.

To illustrate the dynamic behavior, in this case a step function was applied in the reflux ratio at 0.5 h changing from 5 to 10, starting the simulation at the steady-state. In Figures 17 and 18, the dynamic behavior of the benzene distillate composition and top temperature for the complete and reduced models are presented. The larger bias presented by the orthogonal collocation method is a consequence of the poor steady-state approximation shown in Figures 14 to 16.

In order to compare only the dynamic response, Figures 19 and 20 present the same results in terms of deviation variables from the initial steady-state. The good agreement of the method of moments with the complete model in terms of gain and dynamic response can be observed.

**Figure 17:** Distillate composition response due to a +100% step change in the reflux ratio at 0.5 h for the complete and reduced models of the BTX column.

**Figure 18:** Top temperature response due to a +100% step change in the reflux ratio at 0.5 h for the complete and reduced models of the BTX column.

**Figure 19:** Distillate composition difference response due to a +100% step change in the reflux ratio at 0.5 h for the complete and reduced models of the BTX column.

**Figure 20:** Top temperature difference response due to a +100% step change in the reflux ratio at 0.5 h for the complete and reduced models of the BTX column.
Distillation Column – Ethanol, n-Propanol and Water

The mixture of ethanol, n-propanol and water, with the specifications given in Table 8, presented in this section was simulated in order to demonstrate the strength of method of moments in representing non-ideal systems. The Peng-Robinson equation of state was used in the vapor phase and the UNIFAC model was used in the liquid phase to evaluate the thermodynamic properties.

Table 8: Distillation column specifications for the ethanol–n-propanol–water system.

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of trays</td>
<td>40</td>
</tr>
<tr>
<td>Feed tray</td>
<td>20</td>
</tr>
<tr>
<td>Feed composition</td>
<td>[0.40 0.20 0.40]</td>
</tr>
<tr>
<td>(benzene, toluene, o-xylene)</td>
<td></td>
</tr>
<tr>
<td>Feed flow rate (kmol/h)</td>
<td>100</td>
</tr>
<tr>
<td>Feed temperature (K)</td>
<td>283.15</td>
</tr>
<tr>
<td>Operating pressure (kPa)</td>
<td>500</td>
</tr>
<tr>
<td>Reflux ratio</td>
<td>5</td>
</tr>
<tr>
<td>Distillate flow rate (kmol/h)</td>
<td>50</td>
</tr>
</tbody>
</table>

Figures 21 to 23 illustrate the behavior of the relative errors for each component and the temperature for different order reductions. Equation (20) shows the criterion used to find the number of necessary collocation points. This relative deviation was calculated between the variables of the complete and reduced model. The maximum acceptable deviation was set to 5%.

\[
\left\| \frac{X^{\text{Complete}} - X^{\text{Moments}}}{X^{\text{Complete}}} \right\| \leq 5\%  \tag{20}
\]

Figures 24 to 27 illustrate the results of the approximation of the composition and temperature profiles using the method of moments and the method of orthogonal collocation. Five internal points were used in each section, which means a reduction of 75%. Both methods presented good accuracy in the reproduction of the composition and temperature profiles, but the method of moments showed a reasonable superiority over the orthogonal collocation.
CONCLUSIONS

The proposed technique of model order reduction of staged separation systems based on the sum of moment-weighted residuals is shown to be superior to the orthogonal collocation method on a discrete domain, allowing a significant reduction in the model order with good quality. Global heat and mass balances are fulfilled in this new method. Moreover, in the orthogonal collocation method the points where the residuals are canceled are fixed, and in the new method moving collocation points are obtained, characterizing a desirable adaptive nature of this technique. The scaling of the discrete independent variable was crucial for the accuracy of the roots of Hahn’s polynomials, avoiding accumulation of round-off errors present even in low-degree polynomial approximations in the original discrete variable. Steady-state and dynamical simulation results of distillation columns suggest the technique can be applied for optimization and control purposes.

ACKNOWLEDGEMENTS

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REFERENCES

Highly-Accurate Model Order Reduction Technique on a Discrete Domain


