On the use of thermographic method to measure fatigue limits

Abstract
Traditional fatigue limit measurements are expensive and time consuming, requiring a large number of specimens and a long time to be completed. An alternative approach is used in this work to obtain the fatigue limit of a cold drawn steel, in a rotating bending machine, by monitoring temperature variations induced by different load range levels in just a few specimens. Comparisons with Dixon’s traditional up-and-down method confirm that this thermographic approach is indeed a much more efficient, faster, and cheaper method to obtain fatigue limits.

Keywords
Fatigue, Fatigue limits, Thermographic method.

1 INTRODUCTION
The fatigue limit is a most important property for practical applications. It is widely used to avoid fatigue failures in long life structural designs, since it quantifies the stress amplitude below which macroscopic fatigue cracks should not initiate under alternated service loads. Since estimations of fatigue properties are intrinsically unreliable [1], experimental determination of fatigue limits is a must to warrant the reliability of engineering designs. Material fatigue limits $S_f$ can be measured by testing small polished specimens under constant amplitude alternated loads, while fatigue limits of structural components $S_o$ can be obtained by testing full size pieces [1].

Albeit traditional fatigue limit measurement techniques based on Dixon’s up-and-down sequential method may require fewer specimens than other approaches, they still need many specimens and very long testing times in universal servo-hydraulic or electromechanical testing machines, or even in dedicated rotating bending machines [2]. Even though, they still are the preferred method in practical applications to avoid coaxing, especially in ferrous alloys, which may induce fatigue strengthening under cyclic loading below but close to the fatigue limit. It may be a problem, for instance, when using Prot’s incremental method to measure fatigue limits [3-4].

Measurement techniques based on resonant ultrasonic tests, primarily used in very high cycle fatigue studies, can be used to speed up fatigue limit measurements by much increasing the test frequencies, but they are not widely applied in practice due to experimental difficulties [5-6]. Nevertheless, a recently proposed alternative thermographic method based on the measurement of temperature increments induced by various load amplitude levels can be a much more efficient, faster and cheaper way of assessing fatigue limits even without cracking the specimens. The main idea behind thermographic methods is that the transition from primarily elastic undamaging load events below the fatigue limit to cyclic elastoplastic damaging events above it is also associated with detectable temperature increments in the fatigue specimens.

De Finis et al [7] investigated the fatigue behaviour of martensitic and precipitation hardening steels by means of the thermography technique. Their thermographic analyses take into account all heat sources involved in fatigue tests, with accurate measurement of temperature relative to dissipative phenomena and an automatatable procedure proposition.

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Fan et al. [8] showed that temperature evolution during the fatigue tests is closely correlated to internal microstructural changes. Good agreements were achieved between results predicted by thermographic techniques with traditional testing procedures.

Guo et al. [9] established an intrinsic energy dissipation model, based on the double exponential regression for one-dimensional distribution of specimen surface temperature variations. According to the authors, this energy method takes intrinsic dissipation as the fatigue damage indicator, eliminating the interference of internal friction on fatigue life evaluations. The analysis indicates that in high-cycle fatigue, processed under constant stress amplitude, the microstructure evolution is characterized by a stable intrinsic energy dissipation rate. They established that fatigue failure would occur after part of this intrinsic dissipation, due to microplastic deformation, has accumulated a threshold value, which would be a material constant independent of the loading history.

Huang et al. [10] proposed three new treatment methods to determine the fatigue limit, by relating the temperature response (caused by dissipated energy) with the applied stress amplitude, using a graphic method.

Palumbo and Galietti [11] proposed a new thermal method named thermoelastic phase analysis, which was used to evaluate the fatigue limit of martensitic steels. Their main idea was that the thermoelastic response of a material under fatigue loading is influenced by the presence of a heat source, which is related to a dissipative phenomenon associated with fatigue damage mechanism. Monitoring this thermoelastic parameter could provide the fatigue limit identification.

Wang et al. [12] explored the use of full-field temperature measurement by infrared thermography to identify the microplasticity evaluation in the very high cycle fatigue regime. An ultrasonic fatigue testing machine and an infrared image system were used to correlate the estimated plastic strain amplitude with the fatigue lives of the material through the Manson-Coffin law.

The main objective of this work is to compare the fatigue limit of a low carbon cold drawn steel measured by traditional techniques with the fatigue limit obtained by the thermographic methodology proposed by La Rosa and Risitano [13], to verify if this new technique can indeed be a viable option to obtain the material fatigue limit.

2 THEORY

Traditional and thermographic procedures to obtain fatigue limit measurements are briefly described next.

2.1 Dixon’s up-and-down method

The up-and-down method is an iterative statistical technique suitable to measure transition properties like the fatigue limit of materials. First, a specimen is tested under a stress amplitude level \( (\sigma_0) \). If it breaks, the next specimen is tested under a stress amplitude \( (\sigma_0) < (\sigma_1) \) decreased by a constant value \( \Delta\sigma_0 \), but if it doesn’t break after reaching a long and sufficiently high number of cycles \( N_m \), the next specimen is loaded by a stress amplitude \( (\sigma_0) > (\sigma_1) \) increased by the same \( \Delta\sigma_0 \) [6]. This sequential process continues until a number of statistically representative number of specimens \( n_t \) is tested [2].

Figure 1 shows a flowchart summarizing the up-and-down method, where \( 0 < C_1 < 1 \) is a constant that multiplies the material tensile strength \( S_t \) to obtain the first stress amplitude level \( (\sigma_0) \); \( C_2 \) is another constant \( (C_2 > 1) \) used to generate the constant stress amplitude increment \( \Delta\sigma_0 \); the integer counter \( k (1 \leq k \leq n_t) \) is used to define both the specimen’s number \( CR_k \) and the stress amplitude level; \( (\sigma_0)_k \); \( F \) and \( T \) represent a false and a true sentence, respectively.
After testing all specimens, Dixon-Mood’s statistical analysis is used to estimate the fatigue limit following the flowchart presented in Figure 2, where: $A$, $B$, and $C$ are constants calculated according to the equations defined in the flowchart.

When the less frequent event LFE is the survival, the number of stress amplitude levels tested on survived specimens is $q_{\text{max}}$; then $m_q$ is the number of specimens that have survived at each stress amplitude level $q$. The lowest stress amplitude level is always $(\sigma_a)_0$, which is associated with $q = 0$.

However, if LFE is the failure, $q_{\text{max}}$ represents the number of stress amplitude levels tested on failed specimens; $m_q$ is the number of failed specimens at each stress amplitude level $q$. The lowest stress amplitude level $(\sigma_a)_0$ is also associated with $q = 0$. The statistical analysis uses these parameters to determine the mean $\mu$ and standard deviation $\varphi$ of the fatigue limit.

**Figure 1: Up-and-down method flowchart.**
In this article, the up-and-down method is used as the reference method to measure the fatigue limit by means of standard rotating bending test procedures, as already done by other authors like Lipski [14], Curá et al. [15], La Rosa and Risitano [13] and Luong [16].

2.2 Thermographic method

It is well known that any material subjected to dynamic elastic loads slightly changes its temperature due to thermoelastic effects [17]. However, for loads above the fatigue limits these temperature variations are much more pronounced because fatigue damage necessarily involves dissipative cyclic plastic strains [13].

Since fatigue damage is an energy dissipative process, Risitano proposed that fatigue failures occur when the plastic deformation energy reaches a constant value characteristic of each material [15, 18–19]. This hypothesis allows a rapid correlation between the temperature $T$ and the number of cycles $N$ at the critical point of a structural component under cyclic loading. Figure 3.a, adapted from [14], shows schematically the surface temperature behaviour of a fatigue specimen under cyclic loading until failure, where the line A means phase II with temperature stabilization and line B means phase II with a constant rate of temperature rise.
Phases I, II and III in Fig. 3a represent the three thermal stages observed during a typical fatigue test. Phase I is characterized by a linear temperature increase from the test beginning until the change of its rate $dT/dN$, to a lower value. It typically corresponds to about 10% of the number of cycles to failure for a specific load level [18]. Phase II is characterized by an increase rate $dT/dN_{II}$ smaller than the previous phase which could be zero for some materials [16]. Finally, phase III is characterized by its abrupt temperature increase rate $dT/dN_{III} >> dT/dN_{II}$ up to the final fracture.

Phase I can be associated to the fatigue starting process or to the crack nucleation stage, due to the formation of intrusions and extrusions primarily caused by the cyclic shear stresses parallel to the smallest crack surface. Phase II can be associated to the crack propagation stage, due to the dislocation movement inside plastic zones that is always ahead crack tips, which are primarily driven by the normal stresses perpendicular to crack surface. Phase III can be associated to fatigue instability condition, when the crack length approaches and reaches its critical length, causing sudden failure. Moreover, the curves $T(N, \sigma_1)$ reduces the temperature variation and increase the number of cycles to failure as the stress amplitude become closer to the fatigue limit $S_L$ as in Fig. 3b,

**Figure 3:** (a) Typical $T \times N$ behaviour during cyclic loading; (b) Effect of the stress amplitude level.
adapted from [18]. On the other hand for \( \sigma < \sigma \text{L} \) the temperature does not change or changes very little, since these low stress amplitudes do not start or propagate fatigue cracks [13, 18]. Note that apostrophe character used in fatigue limit symbol \( \sigma \text{L} \) means that it is referred to the rotating-beam specimen.

Based on the typical \( T \times N \) behaviour of fatigue specimens, Risitano proposed to determine fatigue limits using phase I temperature variation \( \Delta T_i \) or increase rate \( \partial T / \partial N \), for several stress amplitude levels, a task that can be done using always the same specimen. To implement it, it was plotted \( \Delta T_i \times \sigma \) or \( \partial T / \partial N \times \sigma \), where \( \Delta T_i = T_i - T_0 \) is the temperature variation in the end of phase I, \( T_i \) is the maximum temperature in the end of phase I and \( T_0 \) is the specimen temperature when test begins. Risitano showed that \( \Delta T_i \times \sigma \) or \( \partial T / \partial N \times \sigma \) have a bilinear trend with very different slopes \( \partial(\Delta T_i) / \partial \sigma \) or \( \partial(\partial T / \partial N_i) / \partial \sigma \), respectively. These two slopes can be used to identify the transition from no fatigue damage below the fatigue limit to damage accumulation above it, and by consequence the fatigue limit of the tested specimen. According to Risitano, operationally the fatigue limit \( \sigma \text{L} \) can be determined by thermographic technique extending the straight line with highest slope until it across \( \sigma \) -axis. This approach will be used in this article.

### 3 MATERIAL AND METHODOLOGY

Basic material properties were obtained through chemical analysis, tensile tests and metallography. Fatigue tests were made in a rotating bending machine under load ratio \( R = -1 \) and frequency \( f = 8,500 \) Hz, enough to reach the proposed number of cycles to characterize an infinity life \( N_\infty = 5 \times 10^6 \) cycles in about 10 hours, supposing as usual that the fatigue limit of steels is determined for lives less than \( 1 \times 10^6 \) cycles. In the thermography tests the specimen surface temperature was measured by an infrared camera. Temperature increase rate of first thermal phase was determined at several stress amplitude levels in order to plot \( \partial T / \partial N \times \sigma \) and determine the fatigue limit.

#### 3.1 Material characterization

Table 1 lists the chemical composition of the low carbon steel used in this article. The mean value of its tensile properties obtained in 3 tests is presented in the Table 2, where \( \sigma_y \) is the yield strength, \( \sigma_u \) is the tensile strength and \( RA \) is the area reduction percentage.

<p>| Table 1: Chemical composition (%) |</p>
<table>
<thead>
<tr>
<th>C</th>
<th>Si</th>
<th>Mn</th>
<th>P</th>
<th>S</th>
<th>Cr</th>
<th>Ni</th>
<th>Mo</th>
<th>Al</th>
<th>Cu</th>
<th>Ti</th>
<th>Nb</th>
<th>V</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.226</td>
<td>0.114</td>
<td>0.510</td>
<td>0.020</td>
<td>0.0028</td>
<td>0.024</td>
<td>0.011</td>
<td>0.003</td>
<td>0.017</td>
<td>0.026</td>
<td>&lt;0.001</td>
<td>&lt;0.003</td>
<td>0.001</td>
</tr>
</tbody>
</table>

<p>| Table 2: Tensile properties |</p>
<table>
<thead>
<tr>
<th>( \sigma_y ) (MPa)</th>
<th>( \sigma_u ) (MPa)</th>
<th>RA (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>576.6</td>
<td>666.6</td>
<td>50.1</td>
</tr>
</tbody>
</table>

Figures 4a and 4b show fined ferrite-pearlite microstructure with non-equiaxed grains in transversal micrographies. Figures 4c and 4d show aligned pearlite colonies, as expected from a cold drawn process with no post heat treatment, in longitudinal micrographies.
3.2 Specimen geometry

The specimens followed ASTM E466 standard [20], see Fig. 5a and 5b. All specimens were machined from the same raw material batch in a CNC lathe, using small cutting feeds. The mean surface roughness was measured $R_a = 0.78 \mu m$, equivalent to a N6 ground finishing [21]. Figure 5c shows a specimen with its central part black painted to increase its emissivity in order to improve infrared camera performance in the thermographic tests. All specimens were dimensionally checked and stored in a humidity controlled environment.

Figure 4: Micrographs: transversal: (a) 200X; (b) 500X; longitudinal: (c) 200X; (d) 500X

Figure 5: Specimen: (a) geometry and dimensions; (b) as received; (c) central part black painted.
3.3 Test equipment

A rotating bending machine RBF 200 was used in all fatigue tests. It works by bending moment application on specimen by positioning a block with a constant mass on a ruler. Each position indicates the applied bending moment in the central cross section of specimen, the supposed critical region, in such a way that to increase or to decrease the specimen stress amplitude level it is only a matter of repositioning the mass. The great advantage of this machine is the load frequency, which can achieve up to 10,000 rpm. Figure 6 shows the RBF 200 used in this article.

![RBF 200: (a) overview; (b) lateral view; Thermographic system: (c) infrared camera and (d) black cloth](image)

In the thermographic test, the specimen surface temperature was continuously measured by an infrared camera FLIR A320, with resolution 320 x 240 pixels, data acquisition frequency 30Hz and temperature sensibility 50mK. The temperature data was analyzed using the software ResearchIR from FLIR. The surface of all specimens was black painted to increase its emissivity, as shown by Fig. 5.c. In addition, a black cloth was used to cover the rotating bending machine and camera. Figure 6.c shows the thermographic system with the infrared camera and Fig. 6.d shows the black cloth.

3.4 Test method

For up-and-down method, the stress amplitude increment was set as $\Delta \sigma = 0.02 \cdot S_a$. The number of cycles to characterize an infinite life was set as $N_a = 5 \cdot 10^6$ cycles. The first specimen was tested under $(\sigma_a) = 0.4 \cdot S_a$ and $n_1 = 25$ specimens were tested in total.

For thermographic method, initially the surface temperature of one specimen was continuously monitored until its failure under $\delta_a = 0.6 \cdot S_a$ in order to study the material three thermal phases behaviour. To find the fatigue limit, four specimens were tested under increasing stress amplitude steps $(\sigma_a) = 0.35, 0.40, 0.44, 0.48, 0.50, 0.52, 0.54, and 0.6$, each one lasting the number of cycles necessary to characterize the first thermal phase $N_1 = 5 \cdot 10^6$ cycles, measured in the previous tests. After finding the various phase I temperature rates for each specimen, their $\partial T / \partial N_1 \times \delta_a / S_a$ curves were plotted to access the fatigue limit measured by thermographic technique $L_{th}$. 

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4 RESULTS

The results obtained with up-and-down and thermographic methods are presented next.

4.1 Up-and-down method

Figure 7 shows the results obtained for each tested specimen and Table 3 shows the number of cycles $N$ that each specimen resisted with its associated final condition: failure or survival.

![Figure 7: Up-and-down fatigue test results.](image)

<table>
<thead>
<tr>
<th>Specimen</th>
<th>$N$</th>
<th>Final condition</th>
<th>Specimen</th>
<th>$N$</th>
<th>Final condition</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>$6.0 \times 10^6$</td>
<td>Survival</td>
<td>14</td>
<td>$3.1 \times 10^6$</td>
<td>Failure</td>
</tr>
<tr>
<td>2</td>
<td>$5.5 \times 10^6$</td>
<td>Survival</td>
<td>15</td>
<td>$5.4 \times 10^6$</td>
<td>Survival</td>
</tr>
<tr>
<td>3</td>
<td>$5.3 \times 10^6$</td>
<td>Survival</td>
<td>16</td>
<td>$3.7 \times 10^6$</td>
<td>Failure</td>
</tr>
<tr>
<td>4</td>
<td>$2.0 \times 10^6$</td>
<td>Failure</td>
<td>17</td>
<td>$3.2 \times 10^6$</td>
<td>Failure</td>
</tr>
<tr>
<td>5</td>
<td>$1.0 \times 10^7$</td>
<td>Survival</td>
<td>18</td>
<td>$5.0 \times 10^6$</td>
<td>Survival</td>
</tr>
<tr>
<td>6</td>
<td>$8.1 \times 10^7$</td>
<td>Failure</td>
<td>19</td>
<td>$5.2 \times 10^6$</td>
<td>Survival</td>
</tr>
<tr>
<td>7</td>
<td>$3.8 \times 10^6$</td>
<td>Failure</td>
<td>20</td>
<td>$2.9 \times 10^6$</td>
<td>Failure</td>
</tr>
<tr>
<td>8</td>
<td>$5.0 \times 10^6$</td>
<td>Survival</td>
<td>21</td>
<td>$5.4 \times 10^6$</td>
<td>Survival</td>
</tr>
<tr>
<td>9</td>
<td>$2.7 \times 10^6$</td>
<td>Failure</td>
<td>22</td>
<td>$1.2 \times 10^6$</td>
<td>Failure</td>
</tr>
<tr>
<td>10</td>
<td>$5.7 \times 10^6$</td>
<td>Survival</td>
<td>23</td>
<td>$5.3 \times 10^6$</td>
<td>Survival</td>
</tr>
<tr>
<td>11</td>
<td>$5.9 \times 10^6$</td>
<td>Survival</td>
<td>24</td>
<td>$1.5 \times 10^6$</td>
<td>Failure</td>
</tr>
<tr>
<td>12</td>
<td>$9.7 \times 10^5$</td>
<td>Failure</td>
<td>25</td>
<td>$5.1 \times 10^6$</td>
<td>Survival</td>
</tr>
<tr>
<td>13</td>
<td>$6.1 \times 10^6$</td>
<td>Survival</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

This table shows the number of cycles $N$ that each specimen resisted and its final condition: failure or survival.
Note that the mean fatigue limit measured by the traditional up-and-down has a convergence tendency because it depends on the total number of tested specimens $n_T$. Figure 8 shows that mean fatigue limit tended to converge starting at 15 tested specimens. In this article it was used the mean value calculated for $n_T = 25$. 

*Figure 8: Mean fatigue limit convergence obtained by up-and-down procedure.*

The up-and-down approach results were then used with Dixon-Mood’s statistical method to calculate the mean value and standard deviation of the fatigue limit, considering the less frequent event as the failure, as summarized in the Table 4.

*Table 4: Fatigue limit obtained from traditional up-and-down method.*

<table>
<thead>
<tr>
<th></th>
<th>$\mu$ (%)</th>
<th>$\varphi$ (%)</th>
<th>$S_{L_ud}^\prime$ (MPa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>46.3</td>
<td>1.1</td>
<td>308.9 ± 7.1</td>
<td></td>
</tr>
</tbody>
</table>

4.2 Thermographic method

Figure 9a depicts the resulting $T_{\text{max}} \times N$ curve for $\sigma = 0.6S_d$. It shows that the phase I is characterized by a small number of cycles ($N_i < 5 \times 10^4$); the phase II includes most of the specimen life ($N_i = 2 \times 10^4$); the phase III is associated with a sudden temperature increase, where the specimen final fracture occurs in a small number of cycles ($N_i \ll N_f$). Figure 9b shows some pictures of the temperature distribution on the specimen surface for the three thermal phases and final rupture. They show that, as expected, the higher temperatures are localized around the smaller section of the specimen, where the final fracture occurred.

Figure 10a shows the results of $T_{\text{max}} \times N$ for other stress amplitudes, and Fig. 10b shows phase I details of Fig. 10.a. Figure 11 shows the maximum temperature variation on the surface of specimen number 2 during increasing load steps. Both temperature increment $\Delta T_i$ and the temperature rate $\partial T/\partial N_1$ increase with the
amplitude of each load step. Figure 12 show the relation between stress amplitude value and temperature increase rate of phase I. Figure 12 also presents the linear fitting using the least square method, done with the experimental points with \( \frac{\partial T}{\partial N_i} > 0.1 \times \frac{\partial T}{\partial N_i} (\sigma_a / S_a = 0.35) \). The fitting curve equations and their associated fatigue limit estimative \( (\partial T / \partial N_i = 0) \) are described in Table 5.

**Figure 9:** Temperature distribution for \( \sigma_a = 0.6 \cdot S_a \): (a) \( T_{\text{max}} \times N \) curve; (b) temperature evolution.

**Figure 10:** Temperature distribution: (a) \( T_{\text{max}} \times N \) curve; (b) phase I details of Fig. 10.a.
Figure 11: \( T_{\text{max}} \times N \) under increasing load steps.

Figure 12: \( \partial T/\partial N \times \delta_{\nu}/S_{\text{tot}} \) for each specimen tested by thermographic technique: (a) SP1, (b) SP2, (c) SP3 and (d) SP4.
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Table 5: Fitting curve equations.

<table>
<thead>
<tr>
<th>SP</th>
<th>Fitting curve</th>
<th>$\sigma_u / S_u$ (%) ($\partial T / \partial N_1 = 0$)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>$\frac{\partial T}{\partial N_1} = 3.6 \frac{\sigma_u}{S_u} - 168.2$</td>
<td>46.9</td>
</tr>
<tr>
<td>2</td>
<td>$\frac{\partial T}{\partial N_1} = 3.6 \frac{\sigma_u}{S_u} - 169.5$</td>
<td>46.6</td>
</tr>
<tr>
<td>3</td>
<td>$\frac{\partial T}{\partial N_1} = 4.1 \frac{\sigma_u}{S_u} - 186.4$</td>
<td>45.9</td>
</tr>
<tr>
<td>4</td>
<td>$\frac{\partial T}{\partial N_1} = 3.2 \frac{\sigma_u}{S_u} - 144.5$</td>
<td>45.4</td>
</tr>
</tbody>
</table>

Using the results from Table 5, it is possible to determine the mean value and the standard deviation of the fatigue limit, as presented in Table 6.

Table 6: Fatigue limit by the thermographic approach.

<table>
<thead>
<tr>
<th>$\mu$ (%)</th>
<th>$\phi$ (%)</th>
<th>$S'_{L,\phi} / S_u$ (%)</th>
<th>$S'_{L,\phi}$ (MPa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>46.2</td>
<td>0.7</td>
<td>46.2 ± 0.7</td>
<td>307.2 ± 4.7</td>
</tr>
</tbody>
</table>

5 DISCUSSION

The fatigue limit $S'_{L,\phi} / S_u = (46.3 ± 1.1)^\%$, measured by traditional up-and-down procedures needed 25 specimens to achieve a stable value, with a relatively small dispersion. The fatigue limit determined by the thermographic method $S'_{L,\phi} / S_u = (46.2 ± 0.7)^\%$ was surprisingly close to and slightly less disperse than the one obtained by the reference procedure, with the results obtained in a much faster way.

Indeed, the thermographic tests used 8 specimens, but could have used only 5 specimens (1 for establish the thermal phases and 4 to obtain the fatigue limit), a task that can be easily completed in only one day of work without even breaking them. Moreover, they yielded essentially the same fatigue limit measured by sequentially testing by up-and-down standard procedures 25 specimens up to failure, or else to run-out after at least $5 \times 10^6$ cycles (a much more laborious task that required about one month of work.)

It is interesting to note that such values are compatible with classic estimates for low-carbon steel components with ground surfaces, namely $S'_{L,\phi} \approx 0.45 \cdot S_u$, as defined in reference [1], a reassuring fact for structural designers.

Finally, although outside the scope of this work, it is necessary to mention that the fatigue limit is just part of the problem when designing for very long, or for hopefully “infinite” lives. While microstructural defects such as inclusions and voids are intrinsically included in $S_u$, small scratches, corrosion pits, and similar incidental surface defects, practically unavoidable in long service lives, may affect the crack initiation process. So, although not yet recognized by most designers or by codes, to avoid crack initiation in any structural component it must be able to resist the service loads in the presence of the most damaging (small) defect it may acquire during its operational life.

In other words, structural components that must last for very long fatigue lives should be designed to work under stresses below their fatigue limits and to be tolerant to undetectable short cracks. Indeed, continuous work under fatigue loads cannot be guaranteed if any of the flaws that they might have can somehow propagate during their service lives. However, despite self-evident, this prudent requirement is still not included in $SN$ or $\Delta N$ fatigue design routines used in practice. Indeed, most long-life designs just intend to maintain the service stresses at the structural component’s critical point below its fatigue limit, $\Delta \sigma < \Delta S_{L,\phi}/\phi_F$, where $\phi_F$ is a suitable safety factor for fatigue applications. So, although such calculations can be quite complex (e.g. when analyzing fatigue crack initiation caused by random multiaxial non-proportional loads), their so-called safe-life philosophy is not that safe.

However, despite neglecting any cracks, most long-life fatigue designs work well in practice. This means that they are somehow tolerant to undetectable or to functionally-admissible short cracks. But the question “how
much tolerant” cannot be answered by $SN$ or $dN$ procedures alone. This potentially important problem can be dealt with by adding short crack concepts to their infinite life design criteria using Fracture Mechanics tools, see for instance [22-23] for further details.

6 CONCLUSION

Thermographic techniques originally proposed by Risitano proved to be really a much faster and easier way to obtain the fatigue limit of the tested low carbon steel. The utilization of a rotating bending machine to access the fatigue limit for both techniques, up-and-down and thermographic, with $R = -1$, produced similar results, yielding values directly comparable with the majority of the available fatigue limits. This new technique proved to have many advantages in relation to classical techniques to obtain fatigue limits, such as the utilization of fewer specimens and the access to the fatigue limit without the necessity of leading the specimens to final failure (complete rupture). Therefore, in the authors opinion, it is time to seriously consider a round-robin to evaluate the possibility of standardizing these thermographic procedures for use in practical applications.

7 REFERENCES


