Logistic evaluation of an underground mine using simulation

Abstract

This paper describes a logistic study about an underground gold mine, belonging to AngloGold Ashanti, where four different layout options could be applied to the tunnels, and also different transportation strategies. Each evaluated layout had its own configuration for shaft and truck fleets. The study was made individually for each year of the mine operation life, determining the necessary transportation capacity to achieve the planned production for that year. Due to the very restrictive traffic options in the tunnels, a framework was developed to represent the tunnels and traffic rules in a discrete-event simulation model. The results pointed the scenario with the lowest necessary transportation capacity to achieve the planned production.

Keywords: transportation capacity, simulation, ARENA.

1. Introduction

AngloGold Ashanti is one of the largest gold producers around the world. Based at Johanesburgo, in South Africa, the company has 23 operations in 11 countries. There are more than 63 thousand employees globally.

In Brazil the main assets are located in the iron quadrangle in the state of Minas Gerais and also in the state of Goiás. The company operates three business units: Córrego do Sítio (in Santa Bárbara, Minas Gerais); Cuiabá-Lamego (in Sabará, Minas Gerais) and Serra Grande (in Crixás, Goiás). Besides this, the company has corporate offices located in the city of Nova Lima.

The largest production portion of the company comes from underground mine and open pits operations of South Africa (40%) and Continental Africa (33%). Brasil is responsible for 9% of its production followed by Australia. United States represents 5% and Argentina 4%.

In the business unit of Cuiabá-Lamego, with the deepening of mining activities, the continuity of operations in a sustainable and profitable way is becoming a challenge. With depth, the continuity of operations are affected by an increase of average trucking distances, ventilation needs, infrastructure and ground conditions.

Inside this context of optimization
and sustainability the transport system plays a key role, mainly in what refers to production rate maintenance in the long term. The fact of having a loading station at level 11 and with the current Business Plan going down to level 24, there will be a great impact on the average trucking distance and as a consequence, fleet increase, investment on infrastructure, ventilation and maintenance.

To search for the best alternative of the transport system that could reach required production levels with minor investment, Anglogold appealed to ARENA simulation software, since traffic in underground mines is a very dynamic process and very difficult to study with deterministic tools.

The concern about underground traffic in mines is not new. It is also subject to simulation studies since the early days of this technique being applied with computers. Hayashi and Robinson (1981) documented a simulation study regarding an underground railroad in a coal mine. They addressed traffic problems in detail, considering crossing lines, single lines and tunnel layouts. Their objective was also achieved for the best train configurations and dispatching strategies to sustain coal production with minimum resources.

The study conducted by Miwa and Takakuwa (2011) is also about a coal mine. They have evaluated an underground conveyor network, another option to retrieve minerals from the mine. In this case, the study was focused in the conveyor velocity, working under a predefined layout. Wu et al. (2013) have developed a simulation study regarding tunnel visualization of underground mines, but the transportation and traffic were not discussed.

When an underground mine uses trucks as the main transportation resource, the tunnel network may have traffic problems similar to a railroad network. Usually, the tunnels are large enough to allow only one truck to pass, sometimes two. Traffic situations like passing or crossing are not easy inside the mine. Almost every tunnel has structures called “mucking bays” or “passing bays”, which are strategically located spaces that can accommodate one truck, sometimes more than one. When a truck is in a tunnel and another comes from the opposite direction, one of them parks into the passing bay and allows the other to pass. This is similar to a single railroad line with a crossing line, like presented at Figure 1.

Since the traffic problems are similar, the solutions developed for railroad could also be applied to this case, with the necessary adjustments. Even the prioritization behavior is the same: loaded trucks should pass and empty trucks should wait. The chosen algorithm was the one proposed by Fioroni et al. (2008), which addresses the line/tunnel restrictions, crossing rules and traffic behavior. The following sections describe how this study was conducted.

The purpose of this work is to demonstrate, through simulation, what is the best transport system for Cuiabá mine. To develop this work some factors were used from which we can highlight the impact of traffic in cycle time.

This variable could not be reached by software available on the market as Fleet and Production Cost, and Talpac with their deterministic approach.

The underground mine problem overview

To keep production rates with the safety levels required, in a profitable way and maximizing value to shareholders, the deepening of the mine must be studied in several aspects. From those we can highlight ventilation, refrigeration, infrastructure, rock mechanics and transport system.

At the current stage, the loading station is located at level 11 while the mining faces are located at level 15 (each panel is level to 66 meters in vertical extent). Considering that the current BUP goes down to level 24, an increase in average trucking distance and in the transport fleet would result in traffic congestion and as consequence this could impact the system production.

In the underground besides trucks there is also traffic from support vehicles, such as Jumbos, keep simbas, scalers and supervisory light vehicles that contribute to the impact of system productivity.

The software packages present in the market as Fleet Production and Cost Analysis from Caterpillar and Talpac make a deterministic approach on fleet evaluation. Talpac, besides the deterministic approach, has the Full simulation tool that makes a probabilistic approach to a fleet of trucks and loaders in a specific route of transport. The probabilistic approach from Talpac allows for the variation of key factors in fleet dimensioning as loader cycle time, trip time, dumping time, availability of fleet and payload of loader. For example if we run the simulation for 90 shifts, for each shift we would have a specific value, extracted from the probability charts.

This probabilistic approach is not sufficient to measure the impact on
traffic conditions caused by the support fleet and crossing lines on transport ramps. As a consequence, Anglogold Ashanti team recurred to Paragon, the representative office of ARENA in South America, to analyze and study the proposed scenarios.

The underground mine used to support this study is located in Brazil, at the Minas Gerais state. The available scenarios to be evaluated are a combination of the following components:

- Tunnel layout
- Traffic directions
- Shaft loading position
- Intermediary silos: quantity and position
- Truck type and capacity

The trucks have mainly three tasks to accomplish: carry the gold ore to a shaft or hopper, carry waste to the shaft or hopper and carry waste to some mined out areas that need to be filled again. Trucks never go loaded to the surface. The mine has a limited number of loaders, which is the same for all scenarios. The loading points are changed according to the production schedule, going deeper at the mine.

After internal discussions and studies, the Anglogold team has selected four scenarios to be evaluated with simulation:

Scenario 1: Original design
This scenario is the original design for the mine, with four main access tunnels and a mix of trucks with capacity of 30 and 45 tons. It is considered the base scenario, used as a reference.

The schematic of the tunnel network is presented at Figure 2. Each color square is a mining point at the level, and a brown square means a passing bay position.

Figure 2
Tunnel schematics for the scenario 1, the base scenario

This scenario has a hopper at level 9 and the shaft is positioned at level 11, providing two unloading points for the trucks.

Scenario 2: Deeper shaft position
This scenario uses the same mix of trucks, but adding a new unloading position at level 16, providing more options for the trucks, minimizing congestions. It is also nearest to the bottom of the mine. The tunnel layout is the same of scenario 1.
Scenario 3: Intermediary silos

This scenario uses the same tunnel network layout and unloading positions of scenario 1, but intermediary silos were added at levels 15, 18, 20 and 22. A fleet of 30 tons trucks is used to bring gold ore to the these silos, and after that, another fleet of 60 tons trucks is responsible for conveying it to the shaft position at level 11.

Scenario 4: Additional access tunnel and traffic changes

This scenario adds a new access tunnel to the scenario 1 layout, assigning it as unidirectionally going down, and another pre-existing tunnel as unidirectionally going up.

The truck fleet mix is also the same as scenario 1, with 30 and 45 tons of capacity. At figure 3 below, we can see layout changes:

Modeling the mine

The simulation tool chosen to build the models was Arena, from Rockwell Automation. The approach to model the tunnel network was the one described by Fioroni et al. (2013), the signal oriented approach. It was chosen because the network had some particularities that should be addressed locally, and this approach allowed that. Situations like prioritization between trucks and the access to the hoppers required a local set of decisions different from the regular truck movement. This approach focuses on the signal intelligence, letting them decide if the truck is allowed to pass or not. Signals were distributed along the model network and each one of them had a different decision expression, considering the other signal’s status, the nearby tunnels situation and other factors relevant to its specific location. At the real mine, they...
do not really have this amount of light signals, but the truck advance is decided visually or by radio instructions, resulting in the same behavior.

The model has considered more than 2000 individual positions where the truck could load, unload, park or wait for other trucks to cross. The animation structure of the tunnel network is presented in Figure 4, where the signals can be seen along the lines.

The real network was too big to be represented, and a greater part of it was not important to the study. So, not all tunnels were represented; only the ones relevant to the process and with truck circulation. It was simplified, by removing irrelevant connections and aggregating common points.

Also, it was assumed that the truck should use only one path/route between positions. This helped to simplify the model and give some “room” in the results, since at the real mine the trucks could avoid tunnels with more traffic, taking better decisions than the model. But it was not considered relevant enough to affect the decision.

The routes were mounted by AngloGold personnel, since they have more knowledge about the mine, and where the trucks should pass on every trip between positions. More than 10,000 routes were created, covering each possible origin-destination pair in the model.

An individual model has been built for each scenario, due to structural differences between them. Evidently, the route’s list had to be updated for each model.

All trucks and loaders are affected by downtimes and maintenance, and every movement of the trucks has a chance to be affected by disturbing vehicles, impacting its travel time. Although the priority in the mine is for the trucks, sometimes these may be affected by vehicles, such as personnel transportation, tunnel maintenance equipment, cars, etc.

Model output

A set of KPIs were implemented in the model to help the system validation and comparison between scenarios, specially travel and activity times and utilization. Also, the scheduled production and simulated production were compared to confirm the goal achievement. A partial view of the output interface can be seen in Figure 5.

In addition, the model output has included the number of trips performed at each route inside the mine, in order to provide the user useful information about potential traffic problems and the most problematic routes, as can be seen in Figure 6.
Model validation

The model was validated by comparing its results with deterministic calculations made for the base scenario (scenario 1).

Scenarios results

Several experiments were made with each scenario, to determine the optimal truck fleet at each year of operation. The objective was to find the lowest fleet, able to achieve 95% or more of the scheduled production.

Also, all results were analyzed by the mining experts to check for coherency.

The model behavior was evaluated with sensitivity experiments.

After that, AngloGold team has approved the model to proceed with scenario experiments.

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The model behavior was evaluated with sensitivity experiments.

In order to compare the scenarios, a new KPI was proposed, since the truck type was not the same for all scenarios and the direct comparison would not be possible. This KPI was named “Total Transportation Capacity” (TTC) and is a sum of capacities of all trucks of the two different fleets measured in tons, as presented below:

\[ TTC = (F_1 \times C_1) + (F_2 \times C_2) \]

where: F1: Trucks of fleet 1;
C1: Truck capacity at fleet 1;
F2: Trucks of fleet 2,
C2: Truck capacity at fleet 2.

The TTC was calculated for all scenarios and used to generate the chart presented at Figure 7 below.

Figure 7
Comparison between scenarios

Evaluating this KPI, scenario 2 and 4 performed noticeably better than 1 and 3. The production has a peak at 2024 and a reduction at 2025. The transportation capacity required for this year in all scenarios can be noted. The following year, 2025, isn’t so demanding, requiring less trucks. These sudden changes in the number of trucks from one year to another are inconvenient and should be avoided.

The other utilized methodology was the transport momentum expressed in tkm per truck. This and the TCC analysis, allowed the creation of a comparison between scenarios in the same base.

Depicted below there are the charts with quantities of trucks per each scenario:

Figure 8
Trucks numbers for each scenario

In sequence we have the average cycle time for each scenario:
Figure 9
Average cycle time for each scenario

And then in the end, we have the average trucking distances for each scenario:

As the production profile considered was the same for all scenarios the tkm charts vary proportionally to trucking distances as in Figure 11 below:

After dividing the tkm by the truck numbers for each scenario, we reach a KPI, that similarly to TCC, allows us to make a comparison between the scenarios on the same basis.

On one hand, this kind of analysis has shown that scenario 4 is more productive when compared to the others. On the other hand, scenario 3, was the least efficient and required a bigger number of trucks to transport the mass of the production plan. In future analyses, those values could be improved if we adopt trucks without ejectors and increase their...
operational capacity.

Regarding the KPI of tkm for each truck in scenarios 1 and 2, we can observe that they are very similar despite the differences in the average trucking distances. This occurs because with shaft deepening, there is a decrease in truck numbers and also smaller average trucking distance. As a result the tkm per truck is very similar to those numbers of scenario 1. Those results can lead us to conclude that shaft deepening is not as impacting as we expected.

To choose the best scenario, Anglogold Ashanti will make the economic analysis of each one and will use also other criteria as implementation time and operational complexity.

3. Conclusion

By the results obtained and model behavior, it is possible to conclude that the railroad algorithms and approach adopted were appropriate to represent underground mine truck traffic behavior. All scenarios could be modeled and considered validated by the mine specialists. This is a relevant achievement because to model restrictive movement is always a challenge. Not the restriction itself, but the entire decision process that has to be present to allow the truck or train to move in this structure.

One weak point in this study is the absence of a dispatch system in the model that will probably exist in the real system. Besides, as it would not be perfect or optimal, this could allow the trucks to choose a better path or decide for a different destination depending on the present situation at the mine. In this case, however, as mentioned before, it was not considered relevant to this study. In fact, the fleet determined with the model will be a little bit higher than the one necessary for the real system. On the other hand, the comparison between scenarios is not affected at all. All of them share the same weaknesses, which become irrelevant when comparing scenario data. They are all affected in the same way and at the same level, meaning the comparison is very reliable.

This study was focused on productivity and fleet size to decide the best scenario. There are other factors involved in this choice, such as the investment necessary to implement the infrastructure, the implementation schedule, and the complexity and risks that are going to be analyzed in a next step and were not objects of this study.

The KPI’s as TTC and tkm pointed out scenario 4 as the best option in both scenarios.

This study showed us the capacity of simulation software to model and represent traffic issues found in underground mines. The fleet dimensioning software available on the market does not allow a more deep and detailed analysis on the traffic and transport system as the analysis did by Paragon using ARENA.

The software Fleet Production and Cost and Talpac, works with a fleet dimensioning for a single face or production area but do not offer tools that consider the traffic influence segment by segment.

4. References


