Brazilian Journal of Chemical Engineering

ISSN 0104-6632 Printed in Brazil www.abeq.org.br/bjche

Vol. 26, No. 02, pp. 331 - 341, April - June, 2009

MODELING AND EXPERIMENTAL STUDY OF HYDRODYNAMIC AND DRYING CHARACTERISTICS OF AN INDUSTRIAL ROTARY DRYER

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(Submitted: July 9, 2008; Revised: September 2, 2008; Accepted: September 26, 2008)

Abstract - The purpose of this work was to analyze the hydrodynamic and drying aspects of a rotary dryer used in a fertilizer industry. A set of equations to predict the solids holdup in the flights, the length of fall, the residence time of particles and the drying variables was evaluated by comparison to experimental measurements performed in an industrial rotary dryer of the Copebras Fertilizer Company, located in Catalão, state of Goias, Center-west of Brazil. Because of precise estimations, these equations may be used to design and predict the solids cascading behavior in industrial rotary dryers. Despite larger deviations, reaching 20%, the drying model can also be used for design calculations and process simulations. *Keywords*: Industrial rotary dryer; Hydrodynamic; Drying.

INTRODUCTION

The worldwide population increased from 3 billion people in 1960 to 6 billion people in 2000. In order to take into consideration the demand for food, the optimization of agricultural productivity is quite important. Fertilizers are products compounded with nutrients that increase the growth and the productivity of plants, improving the natural soil fertility or giving back the elements taken away from the soil due to erosion or to previous cultures.

In the production of granulated fertilizers, the raw material (water, ammonia, sulphuric acid and steam among others) are dosed in the equipment called granulator and its goal is to adequate the product to the chemical specifications and increase the size of the particles until they reach the desired standard (between 2 and 4 mm). After this process, there is

the drying operation, which is responsible for removing the volatile substances used in the granulation.

Drying, being one of the most energy-intensive operations, is of great importance in the fertilizer industry. Despite its importance, in many cases the design and operation of dryers is done according to empiricism, based on the "experience" of engineers.

Rotary drums are often used for drying in the fertilizer industry. The dryer consists basically of a cylindrical shell inclined at a small angle to the horizontal. Wet feed is introduced into the upper end of the dryer and the dried product withdrawn at the lower end. The inside of the shell is equipped with lifting flights.

As the dryer rotates, the solids are picked up by the flights and are conveyed for a certain distance around the periphery before dislodging and falling back as a rain of particulate material through a hot

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air stream. The majority of the drying occurs during this period, when the solids are in intimate contact with the air. Therefore, a good flight design is essential to promote the gas—solid contact that is required for rapid and homogeneous drying (Baker, 1988).

The movement of particles in rotating drums depends on of flights and shell design as well as on the operating conditions. Thus, rotary dryers represent one of the greatest challenges in theoretical modeling of dryers (Sherrit et al., 1993). The complex combination of particles being lifted by the flights, sliding and rolling, then falling in spreading cascades through an air stream and re-entering the bed at the bottom, possibly with bouncing and rolling, is very difficult to analyze (Kemp, 2004). Figure 1 shows a rotary dryer and Figure 2 shows a scheme of the movement of solids inside this dryer.

Knowledge of the quantity of solids held up in the flights is essential to ensure that the drum loading is

close to optimum. If the flights are underfilled, the dryer will be operating below capacity and therefore inefficiently. On the other hand, excessive overloading of the drum will result in a proportion of the material being transported by kiln action. This will reduce the average solids residence time and may be detrimental to product quality (Baker, 1988).

The modeling of drying is another challenge in this process. This modeling needs mass and energy balance equations applied to both fluid and solid phases and requires constitutive equations for the heat transfer coefficient, the drying kinetics and the equilibrium moisture content of the solid material.

The purpose of this work was to analyze some existing models to forecast the hydrodynamic and drying variables of an industrial rotary dryer for granulated fertilizers (GTSP). The industrial dryer of the present work is set up in Copebras Fertilizer Company located in Catalão, state of Goias, Centerwest of Brazil.

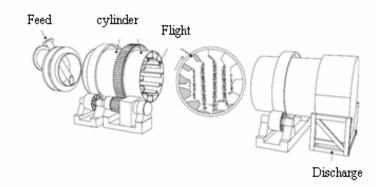


Figure 1: Scheme of a typical flighted rotary dryer

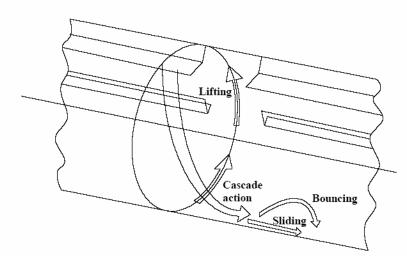


Figure 2: Scheme of the solids movement inside the dryer

HYDRODYNAMIC AND DRYING EQUATIONS

Solids Holdup in the Flights

A certain dryer may incorporate one or more different types of flights (Lisboa et al., 2007). A sufficient number of flights must be distributed across the drum, such that the volume of material transported by the flights is between 10 and 15% of the total material volume within the dryer (Baker, 1983). The number and shape of the flights influence the amount of material present in the rotary dryer. Baker (1983) also suggests that the volume occupied by the load of solids in the rotary dryer should also be between 10 and 15% of the total dryer volume.

For the design of the flights, several researches have developed procedures based on characteristics of the particulate material and the operating conditions. Schofield and Glikin (1962) derived an equation to evaluate the dynamic angle of repose (ϕ) of a powder as a function of its dynamic friction coefficient (μ). If a powder is poured on a flat surface, it will form a pile whose angle with the horizontal plane is called the static angle of repose. This angle of repose is affected by the powder cohesivity. Particles within a flight will also display an angle of repose, with a horizontal plane, which will depend on the angular position of the flight. Since the angle of repose is affected by the drum rotation speed, it is called the dynamic angle of repose.

Kelly and O'Donnel (1977) have developed a measuring procedure for the dynamic friction coefficient (µ). They have also reviewed the equations that relate the drum and flight loading. Baker (1983) showed how the dynamic angle of repose could be used to calculate the solids holdup of a flight at any angular position.

Figure 3 presents a scheme of the flights with three segments, indicating the main dimensions and variables that will be used in the equations developed in this work

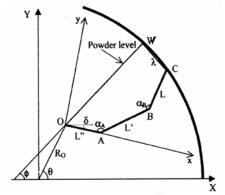


Figure 3: Scheme of the two sets of coordinates in a three-segment flight

The correlation of Schofield and Glikin (1962) that relates the dynamic angle of repose (ϕ) to the dynamic coefficient of friction (μ) of the powder, the angular position (θ) of the tip, the radial position (R_0) of flight tip, and the rotation speed of the drum is shown here as Equation (1). This equation was determined from an equilibrium balance of the forces acting on a particle, which is about to fall from a flight.

$$\tan \phi = \frac{\mu + R_0 \frac{\omega^2}{g} (\cos \theta - \mu \sin \theta)}{1 - R_0 \frac{\omega^2}{g} (\sin \theta - \mu \cos \theta)}$$
(1)

The flights of the industrial dryer used in the present work are of the three-segment type. The equations to predict the solids holdup in a dryer with three-segment flight was based in the work of Revol et al. (2001). Lisboa et al., 2007 used this methodology for flights with two segments and obtained good predictions of hydrodynamic behavior of a pilot scale rotary dryer.

In Figure 3, the flight can be characterized by the segment lengths L, L' and L", their angles α_A and α_B and the radius R_o of the circle described by the flight tip O as the drum rotates. The two sets of Cartesian coordinates are considered. The origin of the (x,y) set is at the flight tip, with the axis along the first segment, this set of coordinates moves as the flight rotates. The origin of the stationary (X,Y) set is at the drum axis, with X-axis located in the horizontal, as shown in Figure 3.

To calculate the volume of powder in the three-segment flight, the coordinates of points A, B and C are first calculated and so the angle δ between the two sets of coordinates is evaluated and the volume of powder is obtained by considering various degrees of filling of the flight with the powder (Revol et al., 2001).

The Equations (2) to (8) locate the three segments in the set of coordinates, where the subscript 1, 2 and 3 refers to respective segments.

$$y_1 = 0 \tag{2}$$

$$y_2 = a_2 + b_2 x (3)$$

with

$$a_2 = x_A \tan(\alpha_A) \tag{4}$$

$$b_2 = -\tan(\alpha_A) \tag{5}$$

$$y_3 = a_3 + b_3 x (6)$$

where

$$a_3 = y_B + xB \tan(\alpha_A + \alpha_B) \tag{7}$$

$$b_3 = -\tan(\alpha_A + \alpha_B) \tag{8}$$

Coordinates of points A, B and C:

$$\mathbf{x}_{\mathbf{A}} = \mathbf{L}^{\prime\prime} \tag{9}$$

$$y_A = 0 \tag{10}$$

$$x_{B} = x_{A} - L'\cos(\alpha_{A}) \tag{11}$$

$$y_{B} = -L'\sin(\alpha_{A}) \tag{12}$$

$$x_{C} = x_{B} + L\cos(\alpha_{A} + \alpha_{B})$$
 (13)

$$y_C = y_B - L\sin(\alpha_A + \alpha_B) \tag{14}$$

The point C in the stationary set of coordinates must satisfy the following equation:

$$X_C^2 + Y_C^2 = R^2 (15)$$

The (x,y) coordinates are related with (X,Y) by the following equations:

$$X_C = X_0 + x_C \cos(\delta) + y_C \sin(\delta)$$
 (16)

$$Y_C = Y_0 + y_C \cos(\delta) - x_C \sin(\delta)$$
 (17)

With: $X_0 = R_0 \cos(\theta)$ and $Y_0 = R_0 \sin(\theta)$.

Substituting Equations (16) and (17) into Equation (15) yields an equation which can be solved for δ , for any angular position θ .

The Equation (18) gives a relation to the powder line.

$$y = x \tan(\lambda) = x \tan(\phi - \delta)$$
 (18)

Its intersection with the line tracing the second segment has the following coordinates:

$$x_2 = \frac{a_2}{\tan(\lambda) - b_2} \tag{19}$$

$$y_2 = a_2 + b_2 x_2 \tag{20}$$

Its intersection with the line tracing the third segment has the following coordinates:

$$x_3 = \frac{a_3}{\tan(\lambda) - b_3} \tag{21}$$

$$y_3 = a_3 + b_3 x_3 \tag{22}$$

The intersection of the solid level line with the drum wall is given by:

$$y_{W} = x_{W} \tan(\lambda) \tag{23}$$

$$x_{W} = -\frac{B_{W} \pm \sqrt{B_{W}^{2} - 4A_{W}C_{W}}}{2A_{W}}$$
 (24)

where

$$A_{W} = 1 + \left[\tan(\lambda)\right]^{2} \tag{25}$$

$$B_{W} = 2X_{0}[\cos(\delta) - \tan(\lambda)\sin(\delta)] +$$
(26)

$$2Y_0[\tan(\lambda)\cos(\delta) + \sin(\delta)]$$

$$C_{W} = R_0^2 - R^2 \tag{27}$$

In this methodology, four degrees of filling the flights by the powder can occur:

1. The powder reaches the wall. This will occur if:

$$\gamma > \arctan\left(\frac{y_C}{x_C}\right)$$
 (28)

In this case, the cross-sectional area occupied by powder can be estimated by Equations (29) and (30).

$$\beta = 2a \sin \left[\frac{\sqrt{(x_C - x_W)^2 + (y_C - y_W)^2}}{2R} \right]$$
 (29)

$$S = \frac{R^{2}}{2} [\beta - \sin(\beta)] + \frac{1}{2} |x_{A}y_{B} + x_{B}y_{C} - x_{C}y_{B} + x_{C}y_{W} - x_{W}y_{C}|$$
(30)

2. The powder does not reach the wall but reaches the third segment. This will occur if:

$$\gamma > \arctan\left(\frac{y_C}{x_C}\right)$$
 (31)

$$\sqrt{(x_3 - x_C)^2 + (y_3 - y_C)^2} < L$$
 (32)

The cross-sectional area occupied by the powder in the flight is:

$$S = \frac{1}{2} |x_A y_B + x_B y_3 - x_3 y_B|$$
 (33)

3. The powder does not reach the third segment, but reaches the second segment. This will occur if:

$$\gamma > \arctan\left(\frac{y_C}{x_C}\right)$$
 (34)

with

$$y_2 > 0 \tag{35}$$

and

$$\sqrt{\left(x_2 - x_B\right)^2 + \left(y_2 - y_B\right)^2} < L \tag{36}$$

Then the cross-sectional area occupied by the powder in the flight is:

$$S = \frac{1}{2} \left| x_A y_2 \right| \tag{37}$$

4. The flight is empty. This will occur if:

$$y_2 < 0 \tag{38}$$

In this work, these equations were used for the estimation of load variation in the flights with their angular position (θ) . The predictions by using these equations have been compared with the experimental data obtained in the industrial dryer.

Length of Fall

The length of particle fall (Y_q) is defined by the length from the flight tip to the bottom of the drum. As particles leave the flights at different angular positions, a range of lengths of fall will be experienced. This information is significant because the drying occurs mainly when the particles are in contact with hot air during the fall. Thus, a longer fall favors a better drying rate. Glikin (1978) proposed Equation (39) to estimate the length of particle fall:

$$Y_{q} = \frac{Y_{0} + \sqrt{R^{2} - X_{O}^{2}}}{\cos(\alpha)}$$
 (39)

The average length of fall is expressed by Equation (40):

$$\overline{Y}_{q} = \frac{D_{0}}{h^{*}(0)\cos(\alpha)} \int_{0}^{h^{*}(0)} \sin(\theta) dh^{*}$$
(40)

Residence Time

In the present work, the equation of Friedman and Marshall (1949) with parameters fitted by Arruda (2007) was used to predict the residence time.

$$\bar{\tau} = Lt \left(\frac{0.1962}{\alpha N_R^{0.9} D} \pm \frac{0.00036 G_f}{G_s d_P^{0.5}} \right)$$
(41)

where: G_s is the mass flowrate of the solid (kg/min), G_f is the gas flowrate (kg/min), d_p is the particle diameter (m), D is the diameter of the dryer (m), and Lt is its length (m), α is given in radians and N_R is given in rpm.

The second term of the Friedman and Marshall equation is negative for concurrent flow and positive for countercurrent flow and thus represents the airflow drag term. The industrial dryer used in the present work is of the concurrent flow type.

Drying Model

The drying model used in the present work was developed by Arruda (2007). The modeling of heat and mass transfer between air and fertilizer grains in rotary dryers was based on the application of mass and energy balance equations for both solid and fluid phases. The following equations form the drying model for concurrent flow (z directions):

a) Variation of air humidity with the length of the dryer

$$\frac{dW}{dz} = \frac{+R_W H}{G_f} \tag{42}$$

b) Variation of moisture in solids with the length of the dryer

$$\frac{dM}{dz} = \frac{-R_W H}{G_s} \tag{43}$$

c) Variation of temperature with the length of the dryer

$$\frac{dT_{f}}{dz} = \frac{-\left[U_{VA}V(T_{f} - T_{S}) + R_{W}H(\lambda + c_{v}T_{f}) \right] + U_{p}\pi DL_{t}(T_{f} - T_{amb})}{G_{f}(c_{f} + W_{c_{v}})}$$
(44)

d) Variation of the solid temperature with the length of the dryer

$$\frac{dT_{s}}{dz} = \frac{\begin{cases} U_{VA}V(T_{f} - T_{s}) + R_{W}Hc_{w}T_{s} \\ -R_{W}H[\lambda + c_{v}(T_{f} - T_{s})] \end{cases}}{G_{s}(c_{s} + W_{c_{1}})}$$
(45)

The inlet air humidity, solid moisture content, and air and solid temperatures are assumed to be constant and known, resulting in the model boundary conditions.

Constitutive Equations

The equilibrium moisture, drying rate and heat transfer equations were adopted from the study by Arruda (2007). The properties of the fertilizers used in Arruda (2007) and in the present study were the same.

Equilibrium Moisture

Arruda (2007) obtained experimental data for equilibrium moisture (M*) of the granulated fertilizer (GTSP) from the static method, by using saturated salt solutions. From a statistic methodology of rival model discrimination, Arruda (2007) concluded that the best equation to represent the equilibrium data for GTSP was the modified Halsey equation (Osborn, 1989). This equation, with the parameters fitted by Arruda (2007), is:

$$M^* = \left[\frac{-\exp(-0.044T_S + 2.080)}{\ln(RH)} \right]^{\frac{1}{1.435}}$$
(46)

with M* on a dry basis, RH (relative humidity) in decimal and T_S in ${}^{\circ}C$.

Drying Rate

Based on experimental data obtained in a thin layer dryer, Arruda (2007) concluded that the best equation to represent the drying kinetics data of GTSP was the Page equation (Page, 1949). This equation, with the parameters fitted by Arruda (2007), is:

$$MR = (M - M^*)/(Mo - M^*)$$

$$MR = exp(-K t^{0.424})$$
(47)

where

$$K=0.304 \exp(-128.282/T_f)$$
 (48)

Overall Coefficient of Heat Transfer

The equation used for the overall coefficients of heat transfer was the one proposed by Miller et al., (1942):

$$U_{VA}=0.145 (N-1)D^{-1}G_{f}^{0.6}$$
 (49)

where: U_{VA} is given in W/m³ K; D is in meters, and the mass velocity of air (G $_f$) is given in kg/m² h.

EXPERIMENTAL METHODOLOGY

Material

Granulated triple superphosphate (GTSP) from Copebras Fertilizer Company used in the experiments had a Sauter mean diameter of 3.1 mm, density of 1.05 g/cm³, and specific heat of 0.29 kcal/kg°C.

Industrial Rotary Dryer

The experimental data of this work were obtained in an industrial rotary dryer of the Copebras Fertilizer Company, located in Catalão, state of Goias, Center-west of Brazil. This dryer is 30 m long, with an internal diameter of 3 m with a capacity of 120 tons per hour. The inclination angle is 2.5°. The flights are of the 3-segment type with the dimensions of 220 x 190 x 50 mm. The angles between the segments of the flights are: 90° between the side and the third segment, 145° between the third and the second segment, and 125° between the second and the first segment. The hot air enters the dryer in concurrent flow with the solids. The flights in the dryer are shown in Figure 4.

The measurements of temperature (dry and wet bulb) were carried out with thermocouples. The solid moisture content was determined by an oven method at 100°C over 24h.

Measurements of the Dynamic Friction Coefficient

In order to measure the characteristic angle, which is used to calculate the friction coefficient in Equation (1), pictures (see Figure 5) were taken of the internal part of the equipment. For each image obtained, the angular position of the flight (θ) and the dynamic angle of repose (ϕ) were measured through the Global Lab Image 2 software.

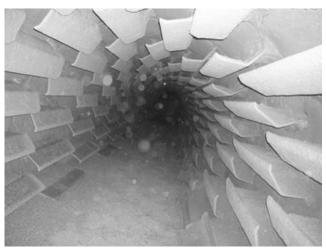


Figure 4: Internal view of the industrial rotary dryer used in the present work

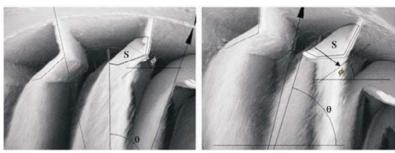


Figure 5: Illustrative pictures of the methodology used to measure the characteristic angle

RESULTS AND DISCUSSIONS

Fluid Dynamic Results

Dynamic Coefficient of Friction

Figure 6 shows the results of the dynamic friction coefficient (μ) of GTSP particles as a function of the flight angular position, obtained from the experimental measurements and those that were calculated from Equation (1).

It is clear that the dynamic coefficient of friction was independent of the flight angular position and this result is in agreement with data reported in the literature (Britton et al., 2006; Revol et al., 2001). The 95% statistical confidence interval for the GTSP dynamic friction coefficient is (0.731; 0.761), with an average value of 0.746.

This value was used to calculate the dynamic angle of repose and then evaluate the flight holdup for any angular position, using the previously shown equations.

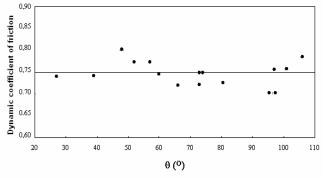


Figure 6: Dynamic friction coefficient for the granulated triple superphosphate (GTSP) as a function of angular position

Material Holdup on the Flight and Length of Fall of Particles

Figure 7 shows the comparison between the holdup measured in the industrial dryer for each flight angular position and the result obtained by the equations previously shown (Eq. 2 to Eq. 38). Figure 8 shows the experimental data of the length of particle fall and the predictions from Eq. (39).

It is interesting to observe in Figure 7 that the flight used in this dryer (three-segment) carries the solids to an angular position of 125°, thereby promoting a good distribution of the material in the sectional area of the drum.

The results of the length of fall (Figure 8) were employed to calculate the average length of particle fall, \overline{Y} (Eq. 40), and the average fall angle ($\overline{\theta}$). The obtained values were, respectively, $\overline{Y} = 2.06$ m and $\overline{\theta} = 53.7^{\circ}$.

The results presented in Figures 7 and 8 show that the equations obtained for the load prediction in the flights by Revol et al. (2001) and for the particle's length of fall by Glikin (1978) allow precise estimations. This fact confirms their potential use for the prediction of solids cascading in industrial rotary dryers.

Residence Time

The residence time was measured in the industrial dryer using tracers (colored GTSP particles). Table 1 shows the comparison between the residence time obtained experimentally and that calculated from Equation 41. These results were obtained at two different drum rotation speeds (3.5 rpm and 4.2 rpm). The average deviation between experimental and calculated values was of 6%.

The results shown in Table 1 indicate that the Friedman and Marshall (1949) equation with parameters fitted by Arruda (2007) can predict satisfactorily the experimental data on residence time in industrial rotary dryers.

Drying Results

Table 2 compares the results of simulation using the drying model (Eq. 42 -49) to experimental data for the four outlet variables (solid moisture content, gas humidity, gas temperature and solid temperature) obtained from two experiments carried out at two different rotation speeds (3.5 rpm and 4.2 rpm). Following the same variable order, the average deviations between these experimental and simulated data were: 29.4 %, 12.4 %, 33.2 % and 20.9 %.

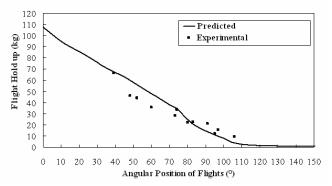


Figure 7: Variation of holdup of flights with the angular position of the flight tip (θ)

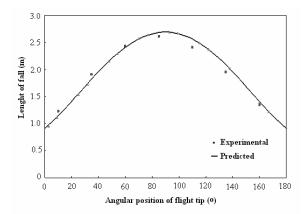


Figure 8: Particle's length of fall as a function of the angular position of the flight tip

Table 1: Residence time: experimental data and values predicted by Equation 41.

	Residence Time (min) 3.5 rpm	Residence Time (min) 4.2 rpm	
Experimental data	13.1	12.0	
Predicted value (Eq. 41)	14.3	12.4	

Table 2: Experimental and calculated drying results for the four outlet variables.

	Rotation: 3.5 rpm		Rotation: 4.2 rpm	
	Experimental Results	Simulated Results	Experimental Results	Simulated Results
Solids moisture content (kg water/kg dry solid)	0.0326	0.0396	0.0297	0.0408
Gas humidity (kg water/kg dry gas)	0.043	0.0382	0.0565	0.0488
Gas temperature (°C)	108	74	106	69
Solids temperature (°C)	99	79	97	76

It can be observed that the deviations of the values predicted by the drying model were larger than the hydrodynamic models (Eqs. 1-40). These larger deviations may be attributed to the fact that the parameters of the Arruda (2007) model were fitted under bench conditions, with temperature and flow rate values much smaller than those encountered in industry. However, industrial forecasts with deviations of 20% can be obtained by this drying model.

CONCLUSIONS

The results obtained in this work allow us to conclude that:

- The methodology used for the prediction of the load in three-segment flights (Revol et al., 2001), as well as for the average particle length of fall (Glikin, 1978), gives estimations that compare well with the experimental data. Therefore, these equations may be used in dryer design and for prediction of the solids cascading behavior in industrial rotary dryers.
- The Friedman and Marshall (1949) equation with parameters fitted by Arruda (2007) can predict satisfactorily (deviations around 6%) the residence time in industrial rotary dryers.
- The deviations of the key drying variables (product moisture content, solids temperature, gas temperature and humidity) predicted from the drying model were of the order of 20%, but still acceptable by the industry.

NOMENCLATURE

a_1	intercept of the line traced	m
	by the first flight segment	
	AO	

\mathbf{a}_2	intercept of the line traced	m
	by the second flight segment	
	AB	
\mathbf{a}_3	intercept of the line traced	m
	by the third flight segment	
	BC	
A_{W}	coefficient defined in	
	Equation (24)	
b_1	slope of the line traced by	m
	the first flight segment AO	
b_2	slope of the line traced by	m
	the second flight segment	
	AB	
b_3	slope of the line traced by	m
	the third flight segment BC	
B_{W}	coefficient defined in	
	Equation (24)	
c_{f}	specific heat capacity of dry	$m^{-2}K^{-1}s^{-2}$
	gas	
c_1	specific heat capacity of	$m^{-2}K^{-1}s^{-2}$
	water liquid	
cs	specific heat capacity of dry	$m^{-2}K^{-1}s^{-2}$
	solid	
$c_{\rm v}$	specific heat capacity of	$m^{-2}K^{-1}s^{-2}$
	water vapor	
C_{W}	coefficient defined in	
	Equation (24)	
d_p	average particles diameter	m
Ď	dryer diameter	m
Do	Diameter of the	
	circumference described by	
	the flight tip	
g	gravity constant	m/s^2
$G_{ m f}$	gas flow rate	kg/min
G` _f	mass velocity of gas	$kg/m^2 h$
Gs	solid flow rate	kg/min
h*	material holdup on the flight	kg
	r 1 2	8

h*(0)	material holdup when the flights are at the beginning of a revolution	kg	yw	and C, respectively ordinate of point W, at the	m
Н	dryer holdup	kα		intersection of the powder level with the wall	
K	constant kinetic of drying	$\frac{\text{kg}}{\text{s}^{-0.424}}$	Y	ordinate in the coordinate	m
L''	length of the third segment	s m	1	set centered on the drum	111
Ľ,	length of the second	m		axis	
L	segment	111	Y_0	ordinate of the flight tip in	m
L	length of the first segment	m	10	the coordinate set centered	111
Lt	dryer length,	m		on the drum axis	
M	solids moisture content	kg of water/kg	$\overline{\mathrm{Y}}_{\mathrm{q}}$	average length of fall	m
		of dry solid	•		_
Mo	initial moisture of solids	kg of water/kg	α	slope of dryer	rad.
		of dry solid	α_{A}	angle between first and	radians
M*	equilibrium moisture of the			second segments in flights	
	solids	of dry solid		of three segments	1:
MR	dimensionless moisture of	-	α_{B}	angle between second and	radians
	solids			third segments in flights of	
N	number of flights	-	0	three segments	
N_R	number of rotations per	rpm	β	angle defined by Equation	
	minute,		9	(29)	radians
R	dryer radius	m	δ	angle of the coordinate set centered on the flight tip with	radians
R_0	distance from the flight edge	e m		the coordinate set centered on	
	to the dryer center	1		the drum axis (the angle	
Rw	drying rate	s^{-1}		shown in Figure 2 is negative)	
RH	relative humidity	- 2	2/	angle of the powder level	radian
S	transversal section area,	m^2	γ	with the first flight segment	radian
	occupied by the flight solids			OA	
T _{amb}	ambient temperature	°C	ρ_{s}	particle density	kg/m ³
$T_{\rm f}$	gas temperature	°C		dynamic angle of repose	radians
Ts	solid temperature	°C	ф	angular rotation speed of the	radians/s
t	Time overall volumetric heat	kWm ⁻³⁰ C ⁻¹	ω	drum	raurans/s
U_{VA}	transfer coefficient	KWIII C	$\overline{ au}$	average residence time	min
Up	heat loss coefficient	kWm ^{-2o} C ⁻¹	θ	angular position of the flight	radians
V	volume of dryer	m ³	U	tip	radians
W	absolute air humidity	kg of water	μ	dynamic coefficient of	_
**	absolute all humaity	vapor/kg of	μ	friction	
		dry air			
X	abscissa in the coordinate	m			
	set centered on the flight tip			REFERENCES	
X _{A, B, C}	abscissa of the points A, B	m			
л, в, с	and C, respectively		Arruda	a, E. B., Comparação do Dese	empenho do
x_{W}	abscissa of point W, at the	m	Sec	cador Roto-Fluidizado com	o Secador
	intersection of the powder		Ro	tatório Convencional: Sec	agem de
	level with the wall		Fer	tilizantes. Tese de Doutorado, F	Programa de
X	abscissa in the coordinate set	m		s-Graduação em Engenharia	
	centered on the drum axis			iversidade Federal de Uberlândia (/
X_0	abscissa of the flight tip in	m		, C. G. J., Cascading Rotary	
	the in the coordinate set			vances in Drying, vol.1: Mujumda	
	centered on the drum axis			emisphere, New York, USA), p 1-5	
y	ordinate in the coordinate	m		, C. G. J., The Design of Flights i	
	set centered on the flight tip			tary Dryers. Drying Technology,	6, 631-653
У А, В, С	ordinate of the points A, B	m	(19	988).	

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