

Deformation of nickel-titanium closed coil springs: an in vitro study

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Objective: The aim of this paper was to determine the amount of deformation in four commercial brands of nickel-titanium closed springs. **Methods:** A total of 130 springs were divided into 13 subgroups, according to their features and manufacturers (Morelli, Orthometric, Ormco and GAC) and activated from 100% to 1000% of the effective length of the nickel-titanium portion present at the spring, at 37 °C. Deactivation data were plotted and deformation was found graphically. The values were compared by analysis of variance and Tukey's *post-hoc* test. **Results:** Springs manufactured by Morelli had the same amount of deformation when they were activated up to 700% of Y activation; springs by Orthometric had the same amount of deformation up to 600-700% of Y; springs by Ormco had the same amount of deformation up to 700-800% of Y; and finally, the majority of springs by GAC had similar deformation up to 800%-1000% of activation. All springs tested could be activated up to 700% without rupture. **Conclusions:** Most subgroups were similarly deformed up to 700% of activation, without rupture of springs. Subgroups 4B, 4C, 4D and 4E showed the same amount of deformation up to 1000% of activation without any rupture at all.

Keywords: NiTi. Deformation. Biomechanics.

Objetivo: o objetivo desse trabalho foi determinar a deformação em molas fechadas de níquel-titânio de quatro marcas comerciais. **Métodos:** cento e trinta molas foram divididas em treze subgrupos, de acordo com suas características e fabricantes (Morelli, Orthometric, Ormco e GAC), com ativação entre 100% e 1.000% do comprimento efetivo de níquel-titânio presente na mola (Y), a 37 °C. Dados de desativação foram coletados e a deformação foi obtida de forma gráfica. Os valores foram comparados por meio de análise de variância e teste *post-hoc* de Tukey. **Resultados:** as molas da Morelli apresentaram a mesma quantidade de deformação considerando-se 700% de ativação de Y; as molas da Orthometric tiveram a mesma quantidade de deformação até 600-700% de Y; as molas da Ormco tiveram a mesma quantidade de deformação até 700-800% de Y; e, por fim, a maioria das molas da GAC apresentou deformação semelhante até 800-1.000% de ativação. Todas as molas testadas puderam ser ativadas até 700% sem ruptura. **Conclusões:** a maioria dos subgrupos se deformou de maneira semelhante até 700% de ativação, sem ruptura das molas. Os subgrupos 4B, 4C, 4D e 4E demonstraram a mesma quantidade de deformação até 1.000% de ativação, sem nenhuma ruptura.

Palavras-chave: NiTi. Deformação. Biomecânica.

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INTRODUCTION

In the late 1960s, the U.S. Navy developed a nickel-titanium alloy known as Nitinol,¹ which had the property of returning to its original shape after being heated above a certain temperature. This property was called “shape memory.” Nitinol was introduced in Orthodontics in the 1970s,² due to its low elastic modulus and good elastic recovery. In the following decade, two new nickel-titanium alloys^{3,4} were introduced in Orthodontics, bringing up a new property to orthodontic therapy: superelasticity (SE).

SE is characterized by a near-to-constant force (during unloading) depicted on the alloy's load/deflection graph, caused by a stress-induced transformation from austenitic to martensitic phase (SIMT), which are two different crystallographic structures that can exist within the same alloy. The image of this near-to-constant force on the graph is referred to as a plateau because of its shape, but it will be termed pseudo-plateau in this paper because it is not completely flat. Each of those two phases has a different elastic modulus, which makes this alloy unique.^{5,6,7} In Orthodontics, it is often desired for nickel-titanium springs to work in its SE plateau, but a high stress is needed to induce SIMT. However, the literature is not clear on how much these springs need to be activated without suffering any significant permanent deformation. There are reports in the literature, without presenting any evidence, of activations of 500% the spring's original length without permanent deformation,^{8,9,10} although imposing no limits to a higher activation. Only one paper¹¹ mentions ruptures in nickel-titanium springs excessively activated, but it does not correlate the rupture to the effective length of the nickel-titanium portion in the spring.

Currently, springs are available in different sizes and several martensitic plateaus, as informed by the manufacturer. This makes the choice for the ideal device for each situation very difficult, especially regarding the size of orthodontic space, force produced, amount of activation and the limit that each device allows for activation without permanent deformation.

Therefore, the aim of this study was to determine the percentage of deformation of four com-

mercially available nickel-titanium closed coil springs subjected to several activations.

MATERIAL AND METHODS

Four groups of springs were established according to the manufacturer: Group 1, Morelli Ortodontia (Sorocaba/SP, Brazil); Group 2, Orthometric (Orthometric Importadora Exportadora Ltda, Marília/SP, Brazil); Group 3, Ormco Co. (Glendora, Ca, USA); and Group 4, Dentsply GAC Int. (Bohemia, NY, USA). Within each group, subgroups of ten springs were determined according to length and force plateau provided by the manufacturer. All ten springs from each subgroup were from the same batch, totaling 130 springs (Table 1).

An EMIC DL2000 (São José dos Pinhais, Paraná, Brazil) universal testing machine equipped with load cell of 0.1kN was used for testing. The entire system was submerged in distilled water at $37 \pm 1^\circ\text{C}$,¹² controlled with a 30-W heater (Termodelfim, São Paulo, Brazil) and a thermostat (Alife, São Paulo, Brazil).

The size of the springs in each group was measured with a digital caliper (Mitutoyo SC-6, Suzano, São Paulo, Brazil) and the averages were calculated to determine the total size of the spring (X), as well as the effective length of the nickel-titanium portion (Y) (Fig 1).

Previously to testing, each spring was adjusted with the aid of a digital indicator of extension and force in order to avoid any looseness of the spring, compromising the true activation of the spring in the test.

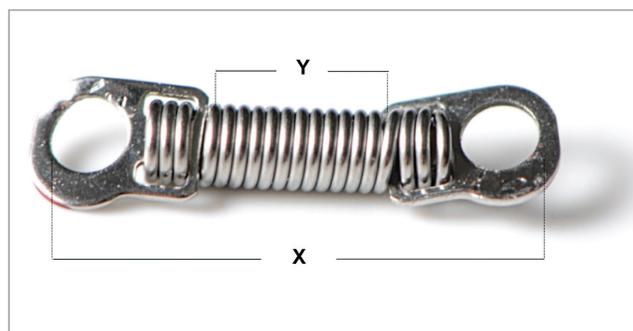


Figure 1 - Nickel-titanium closed coil spring, the X dimension corresponds to the total length of the spring and the Y dimension corresponds to the length of the nickel-titanium portion.

Table 1 - Commercial brands and groups division.

Commercial brand	Specification	Length (mm)*	X (mm)	Y (mm)	Force plateau (gf)*	Subgroup	n
Group 1 (Morelli Ortodontia, Brazil)		7	8.6	2.3	250	1A	10
		9	10.3	3.9	250	1B	10
Group 2 (Orthometric, Brazil)		7	6.8	2.1	175	2A	10
		9	8.9	4.1	250	2B	10
Group 3 (Ormco, USA)	Light	9	8.85	3.25	80	3A	10
	Heavy	9	9	3.1	150	3B	10
Group 4 (GAC, USA)	Sentalloy 25g	10	8.5	3.2	25	4A	10
	Sentalloy 50g	10	8.5	3.2	50	4B	10
	Sentalloy 100g	10	8.5	3.2	100	4C	10
	Sentalloy 150g	10	8.5	3.2	150	4D	10
	Sentalloy 200g	10	8.5	3.2	200	4E	10
	Sentalloy 250g	10	8.5	3.2	250	4F	10
	Sentalloy 300g	10	8.5	3.2	300	4G	10

* information supplied by manufacturer.

The springs were activated to 100% of Y, and then returned to their original position. The test continued to 200%, 300%, 400%, 500%, 600%, 700%, 800%, 900%, 1000% of Y. A dedicated software (EMIC - Equipamentos e Sistemas de Ensaio Ltda, São José dos Pinhais, PR, Brazil) registered, in raw format, the force values obtained throughout the trial. The test was performed at 20 mm/min.

The data obtained were exported to Microsoft Office Excel 2007 (Microsoft, Redmond, USA) in which the amount of deformation was graphically identified at each activation. Deformations were only assessed in the subgroups at the activation that presented SE behavior, as determined according to the methods described in the literature.¹³

Deformation values were transferred to SPSS™ software, v. 16.0 (Chicago, Illinois, USA) in which analysis of variance was carried out in order to identify differences between groups, followed by Tukey's *post-hoc* test to compare subgroups, since data were normally distributed.

RESULTS

Deformations of subgroup 1A springs from 400% to 700% of activation of Y were similar; deformations at 800% of activation were larger than the activations from 400 to 600%, but similar to 700%;

while deformations at 900% and 1000% of activation were the same, but different from all others activations; there was no rupture to these springs. In subgroup 1B, deformations at 400% to 800% of activation were the same; deformation at 800% of activation was the same as 900% of activation, which was equal to 1000% of activation; in this subgroup, one spring ruptured at 1000% activation (Table 2).

Deformations of subgroup 2A springs occurring from 400% to 700% of activation were similar; deformations at 800% were different from those that occurred from 400 to 600% of activation, but similar to those at 700% of activation; above 800% of activation deformations were similar; one spring ruptured at 800% of activation, two at 900%, and three at 1000%. In subgroup 2B, from 400% to 600% of activation, deformations were the same; deformation caused at 600% was equal to the one caused at 700%; at 800% of activation, deformation was equal to 700% of activation; five springs ruptured at 800% of activation, four at 900%, and one at 1000% of activation (Table 3).

Deformations caused at 400% to 700% of activation in subgroup 3A were equal, but different from deformations that occurred at 800% to 1000% of activation, which were equal to each other; five springs ruptured at 900% of activation; from the five springs remaining, two ruptured at 1000% of activation and

tree remained intact. Subgroup 3B did not show SE behavior, so no comparison was performed. In subgroup 3C, deformations that occurred at 600% to 800% of activation were equal, with deformation at 800% being the same as the deformation at 900% of activation, which was the same deformation that occurred at 1000% of activation; four springs of this subgroup ruptured at 1000% of activation (Table 4).

In subgroup 4A, deformations that occurred at 400% to 800% of activation were equal to each other and different from deformations occurring at 900% and at 1000% of activation, which were equal.

In subgroups 4B, 4D, 4C, and 4E, all deformations were the same at 400% to 1000% of activation for the first two subgroups, at 300% to 1000% of activation for subgroup 4C, and at 500% to 1000% of activation for 4E. In subgroup 4F, deformations were equal at 400% to 800% of activation, but different at 900% and 1000%. In subgroup 4G, deformations were equal at 500% to 800% and different at 900% and 1000%. None of the springs in subgroups 4A, 4B, 4C, 4D, 4E, and 4F ruptured. Only one spring in subgroup 4G ruptured at 900% of activation and two springs at 1000% (Table 5).

Table 2 - Average deformation in millimeters (SD in parenthesis) and in percentage values of the total length of group 1 springs.

Activation	Subgroup 1A Deformation			Subgroup 1B Deformation		
	n	%	mm	n	%	mm
400%	10	2.6%	0.06 (0.05) ^A	10	1.3%	0.05 (0.07) ^A
500%	10	3.9%	0.09 (0.05) ^A	10	3.1%	0.12 (0.08) ^A
600%	10	3.9%	0.09 (0.11) ^A	10	5.6%	0.22 (0.18) ^A
700%	10	9.1%	0.21 (0.09) ^{AB}	10	7.7%	0.30 (0.33) ^A
800%	10	17.4%	0.40 (0.18) ^B	10	16.4%	0.64 (0.50) ^{AB}
900%	10	29.6%	0.68 (0.26) ^C	10	36.4%	1.42 (0.68) ^{BC}
1000%	10	35.2%	0.81 (0.36) ^C	9	55.9%	2.18 (1.28) ^C
p		< 0.001			< 0.001	

Table 3 - Average deformation in millimeters (SD in parenthesis) and in percentage values of group 2 springs.

Activation (%)	Subgroup 2A Deformation			Subgroup 2B Deformation		
	n	%	mm	n	%	mm
400%	10	10.0%	0.21 (0.18) ^A	10	6.6%	0.27 (0.18) ^A
500%	10	13.8%	0.29 (0.24) ^A	10	14.4%	0.59 (0.26) ^A
600%	10	15.7%	0.33 (0.28) ^A	10	22.4%	0.92 (0.37) ^{AB}
700%	10	36.2%	0.76 (0.38) ^{AB}	10	36.8%	1.51 (0.84) ^{BC}
800%	9	66.2%	1.39 (0.68) ^{BC}	5	44.1%	1.81 (0.63) ^C
900%	7	96.7%	2.03 (0.84) ^C	1	81.2%	3.33
1000%	4	102.4%	2.15 (1.74) ^C	0	-	-
p		< 0.001			< 0.001	

Table 4 - Average deformation in millimeters (SD in parenthesis) and in percentage values of the total length of group 3 springs.

Activation (%)	Subgroup 3A Deformation			Subgroup 3C Deformation		
	n	%	mm	n	%	mm
300%	10	3.7%	0.12 (0.08) ^A	-	-	-
400%	10	6.5%	0.21 (0.10) ^A	-	-	-
500%	10	9.5%	0.31 (0.16) ^A	-	-	-
600%	10	17.5%	0.57 (0.23) ^A	10	17.7%	0.55 (0.24) ^A
700%	10	42.1%	1.37 (0.37) ^A	10	31.6%	0.98 (0.39) ^A
800%	10	107.1%	3.48 (1.58) ^B	10	66.1%	2.05 (1.05) ^A
900%	5	147.1%	4.78 (0.98) ^B	10	120.0%	3.72 (1.81) ^B
1000%	3	137.5%	4.47 (3.67) ^B	6	154.5%	4.79 (1.38) ^B
p		< 0.001			< 0.001	

- Non SE.

Table 5 - Average deformation in millimeters (SD in parenthesis) and in percentage values of the total length of group 4 springs.

Activation	Subgroup 4A Deformation			Subgroup 4B Deformation			Subgroup 4C Deformation			Subgroup 4D Deformation		
	n	%	mm	n	%	mm	n	%	mm	n	%	mm
300%	-	-	-	-	-	-	10	2.2%	0.07 (0.05)	-	-	-
400%	10	3.4%	0.11 (0.09) ^A	10	2.2%	0.07 (0.05)	10	2.2%	0.07 (0.06)	10	3.4%	0.10 (0.07)
500%	10	2.5%	0.08 (0.05) ^A	10	2.2%	0.07 (0.06)	10	2.5%	0.08 (0.05)	10	4.1%	0.13 (0.13)
600%	10	3.4%	0.10 (0.12) ^A	10	2.2%	0.07 (0.06)	10	2.5%	0.08 (0.06)	10	4.1%	0.13 (0.13)
700%	10	2.8%	0.11 (0.08) ^A	10	2.2%	0.07 (0.06)	10	2.5%	0.08 (0.06)	10	3.4%	0.10 (0.12)
800%	10	14.0%	0.45 (0.29) ^A	10	1.6%	0.05 (0.05)	10	2.5%	0.08 (0.04)	10	3.4%	0.10 (0.12)
900%	10	59.7%	1.91 (1.02) ^B	10	1.3%	0.04 (0.04)	10	1.3%	0.04* (0.07)	10	3.8%	0.12 (0.19)
1000%	10	44.1%	1.41 (0.96) ^B	10	-0.6%	-0.02 (0.14)	10	1.3%	0.04* (0.25)	10	2.8%	0.09* (0.19)
p		< 0.001			0.076			0.965			0.981	

Activation	Subgroup 4E Deformation			Subgroup 4F Deformation			Subgroup 4G Deformation		
	n	%	mm	n	%	mm	n	%	mm
300%	-	-	-	-	-	-	-	-	-
400%	-	-	-	10	4.1%	0.13 (0.05) ^A	-	-	-
500%	10	1.6%	0.05 (0.04)	10	4.1%	0.13 (0.07) ^A	10	3.4%	0.10 (0.09) ^A
600%	10	0.6%	0.02 (0.03)	10	3.8%	0.12 (0.08) ^A	10	3.4%	0.10 (0.08) ^A
700%	10	0.9%	0.03 (0.03)	10	3.4%	0.11 (0.06) ^A	10	1.6%	0.05 (0.05) ^A
800%	10	-0.01	-0.02* (0.18)	10	0.9%	0.03* (0.07) ^A	10	0.9%	0.03* (0.86) ^A
900%	10	1.6%	0.05* (0.27)	10	12.5%	- 0.4 (0.23) ^B	9	38.1%	1.22 (1.41) ^B
1000%	10	1.6%	0.05* (0.38)	10	72.5%	2.32 (0.66) ^C	7	89.7%	2.87 (1.11) ^C
p		0.975			< 0.001			< 0.001	

* Non significant values.

- Non SE.

DISCUSSION

All springs tested could be activated up to 700% without rupturing, some subgroups however, showed more resistance to rupture. Springs in subgroups 1A, 4A, 4B, 4C, 4D, 4E, and 4F did not rupture up to the length tested, while the ones in subgroups 1B, 3B, and 4G only ruptured at 1000% of activation. Springs of subgroup 3A began to rupture at 900%, and the ones in Group 2 began to rupture

at 800% of activation. Comparison of these values is difficult because the literature mentions activations only up to 500%,^{8,9,10} and only one study¹¹ tested springs until they ruptured. In this last study, however, activations were not correlated to the percentage of activation in relation to Y. Despite the risk of rupture being one of the determinant factors to how much a spring can be activated, there are other more important factors, such as deformation.

In most springs of Groups 1, 2, and 3, there was no difference between deformation up to 700% of activation. From that percentage of activation on, deformations increased (except for subgroups 2B and 3C). Even at the smallest activations where SIMT occurred (mostly at 400%), there was already a small deformation that remained stable until 700% of activation, which could be due to stress relaxation of the springs. An interesting fact is that all springs in groups 1 and 2 showed resistance to rupture up to approximately 36% of deformation, and started to rupture above that amount. Deformations measured by this research in nickel-titanium springs may have happened partially because of stress relaxation, residual permanent deformation,¹⁴ and reversible martensitic deformation, which is reversible upon heating above a certain temperature, due to shape memory (Fig 2).

Springs in group 4 ruptured and deformed less than in other groups. In subgroups 4B, 4C, 4D, and 4E, deformation was the same in all activations, even at 1000% of activation, deformations were not clinically significant and were smaller than 2.8%. Subgroups 4A, 4F, and 4G showed the same amount of deformation up to 800% of activation, with maximum deformations of 14%, 0.9%, and 0.9%, respectively. It is clear that, even with a subjective assessment, springs in group 4 were superior when compared to the ones in other groups in relation to deformation and resistance. Similarly to springs of groups 1 and 2, springs of subgroup 4G started to rupture above 38% of deformation.

From a clinical standpoint, even with significant deformations of about 30%, some springs could still be efficient depending on the situation they are used. When closing pre-molars spaces (Fig 3), nickel-titanium springs are normally attached from hooks on the first molars to hooks on the canines (around 23 mm of distance),¹⁵ and after a 7 mm space closure, they would still be active over the 16-mm space left. Thus, if a spring of subgroup 1A (8.6 mm in total length) is attached to the molar hook, stretched to 900% and then engaged over the hook of the archwire during deactivation, it would be effectively activated 14.4 mm and it would remain active up to 7.4 mm of activation with constant force. With a slight difference, one spring from subgroup 1B (10.3 mm) would be active from 12.7 to 5.7 mm (Fig 4). In those two clinical situations, deformations smaller than 7.4 mm and

5.7 mm, respective to each situation, would be considered clinically irrelevant. However, there are two other variables that should be considered when using nickel-titanium springs: one is the desired force, since the force plateau decreases with increased activation;^{11,16} and the second is the relationship between the spring's clinical work range (Fig 3) and the SE plateau length, because even at a SIMT, the dimensions that are clinically used in Orthodontics could make the spring work outside its SE plateau (Fig 4), thus acting in a SE way only after some space is closed or even never acting in a SE way at all.

The decrease of inclination and increase of length in force plateau with activation occurs because stress is not evenly distributed throughout the spring with activation. As activation is gradually increased, there is a tendency for more areas of the spring to be stressed enough to produce a SIMT; thus, with more areas going through reverse transformation, more "superelastic" the spring becomes. For that reason, limiting nickel-titanium springs activation with the purpose of maintaining forces at a low level is illogical. Moreover, it appears to be a good idea to overactivate those springs upon affixation, in order to improve the springs ability to produce constant and relatively lower forces.¹⁷ That directly connects to the fact that the vast majority of nickel-titanium materials does not behave in a superelastic manner when used in Orthodontics, due to the fact that they are not activated enough to produce SIMT. Large springs will not work properly since not enough stress is produced (Fig 5);¹⁷ thus, a pseudo-pla-



Figure 2 - Nickel-titanium closed coil spring, before activation (B) and after 900% of activation (A). After heating it above a certain temperature (Af), the martensitic deformation will resume due to the shape memory effect.

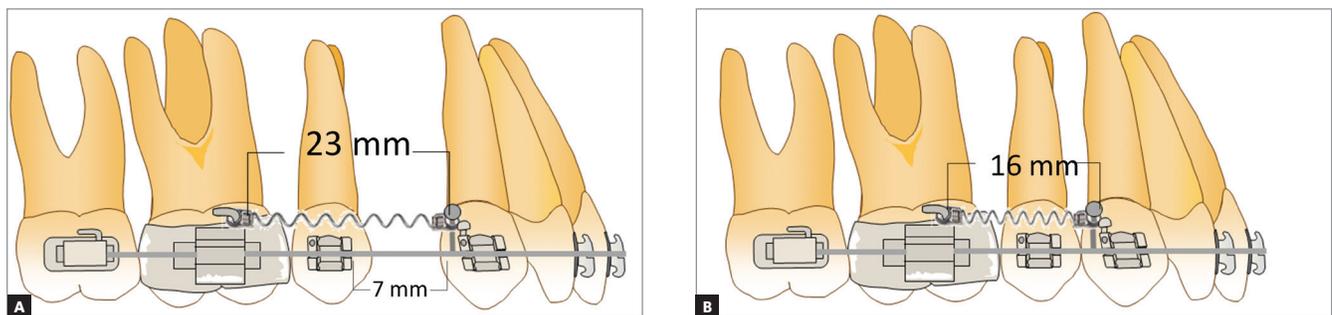


Figure 3 - Space closure after extraction of first premolars where a nickel titanium spring was attached to a hook from the first molar to a hook distal to the canine (23mm distance), remaining active even after space closure (minus 7mm of pre-molar space).

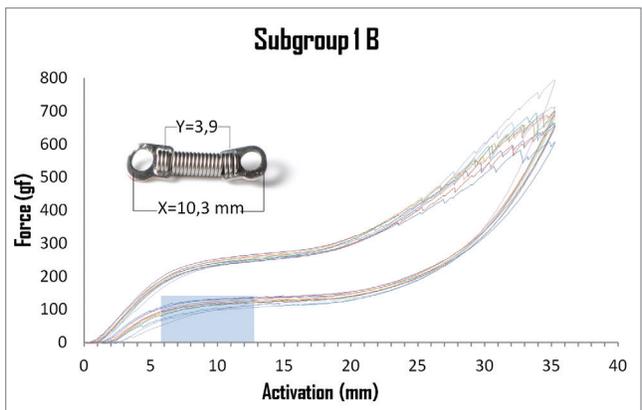
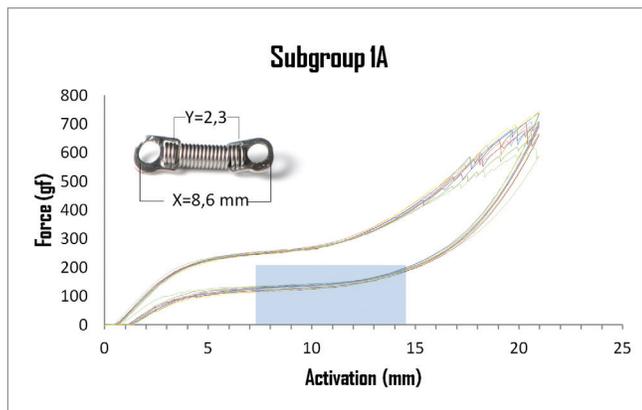


Figure 4 - A) Load/deflection graph for the springs of the subgroup 1A activated at 90% of Y (20.7mm of activation or 29.3mm if the size of the spring is accounted). The blue box corresponds to the distance between the hook of the first molar and a hook distal to the upper canine (minus size of the spring), as in Figure 3 (23mm minus X). Note that to take full advantage of the springs' SE properties, an increase of approximately 3mm in the eyelets (not in nickel titanium portion) would be required in order to maintain the force in the SE plateau. That would shift the blue box to the left the same 3mm. B) Same situation on the subgroup 1B, however, full SE capability would not be achieved in last 2mm or so of space closure, since the force would start to decrease due to lack of stress.

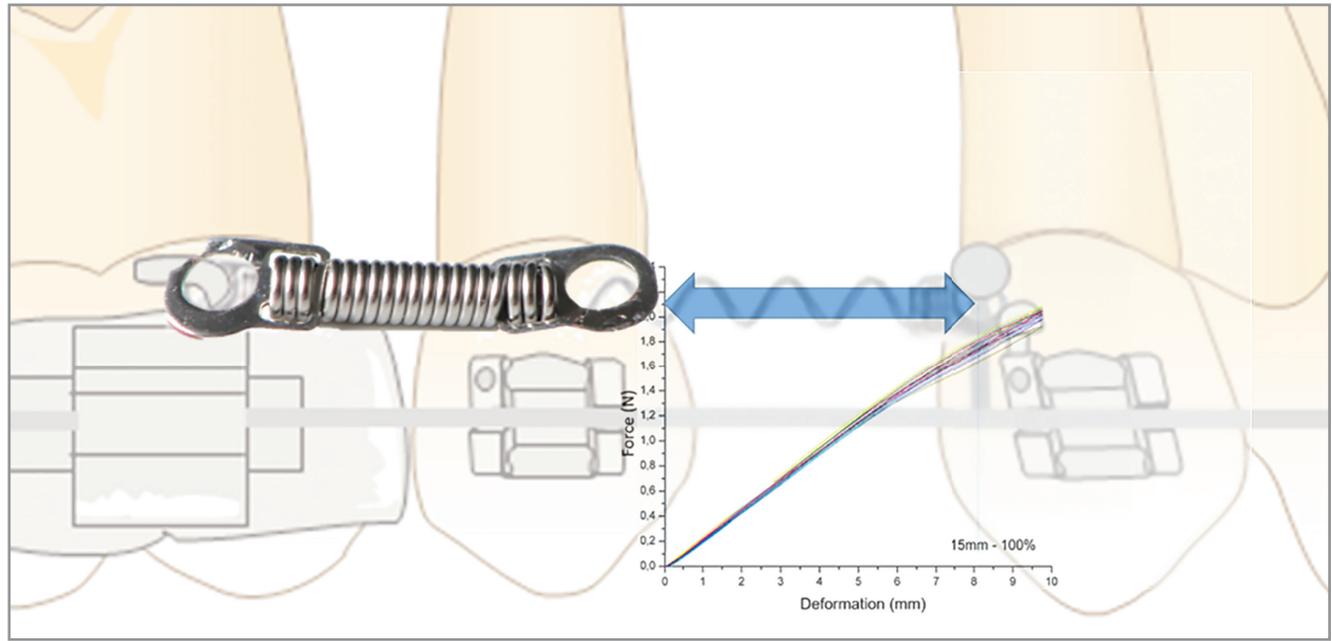


Figure 5 - A 15-mm long nickel-titanium spring (nickel-titanium portion with 9.8mm), activated 9.8mm. A span of activation from the hook of a first molar to the canine, from 23mm to 16mm (similar to Figure 3), is shown by the blue arrow. In this case, due to the springs length, that activation would account 8mm, deactivating to 1mm after space closure. Note that no superelasticity will not exist in this spring at this activation.

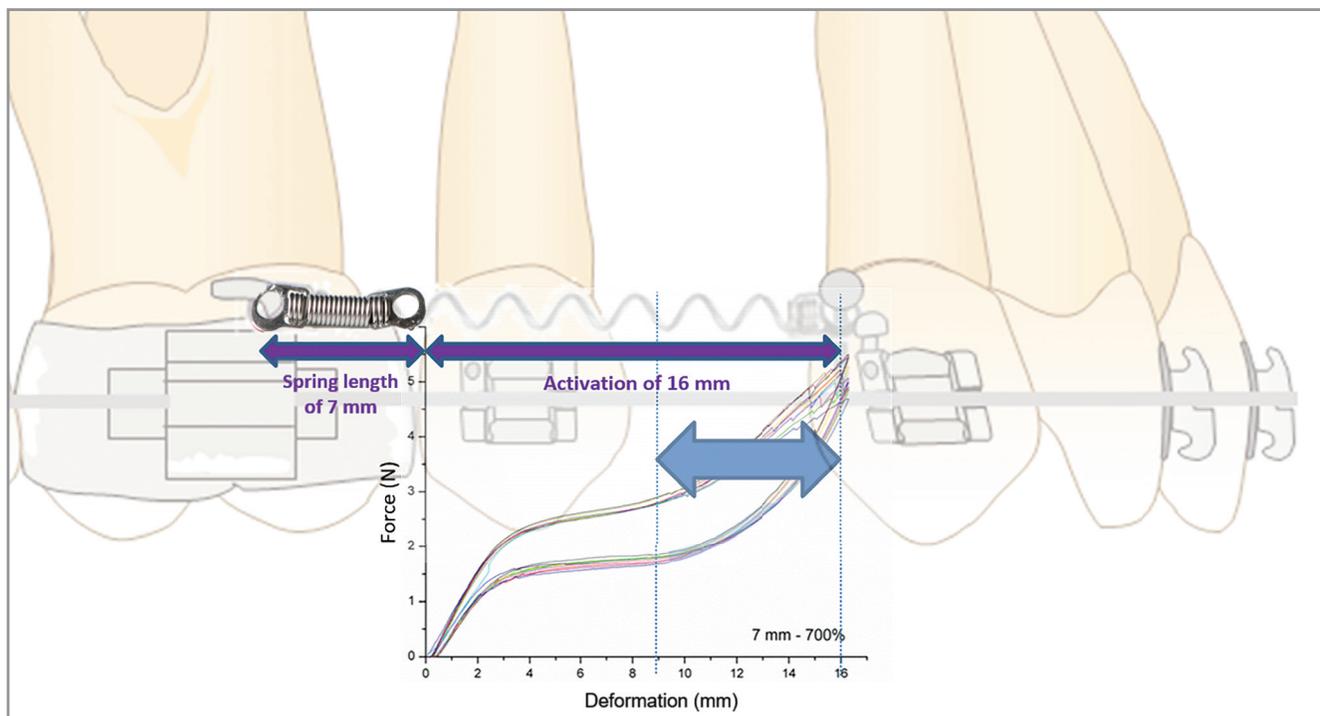


Figure 6 - A 7-mm long nickel-titanium spring (2.3mm of nickel-titanium portion) activated approximately 16mm, which would result in an activation of 23mm. It can be observed that due to the shape of the load-deflection graph, the pseudo-plateau area, or the near-to-constant force, of the spring would not be used during a 7mm space closure.

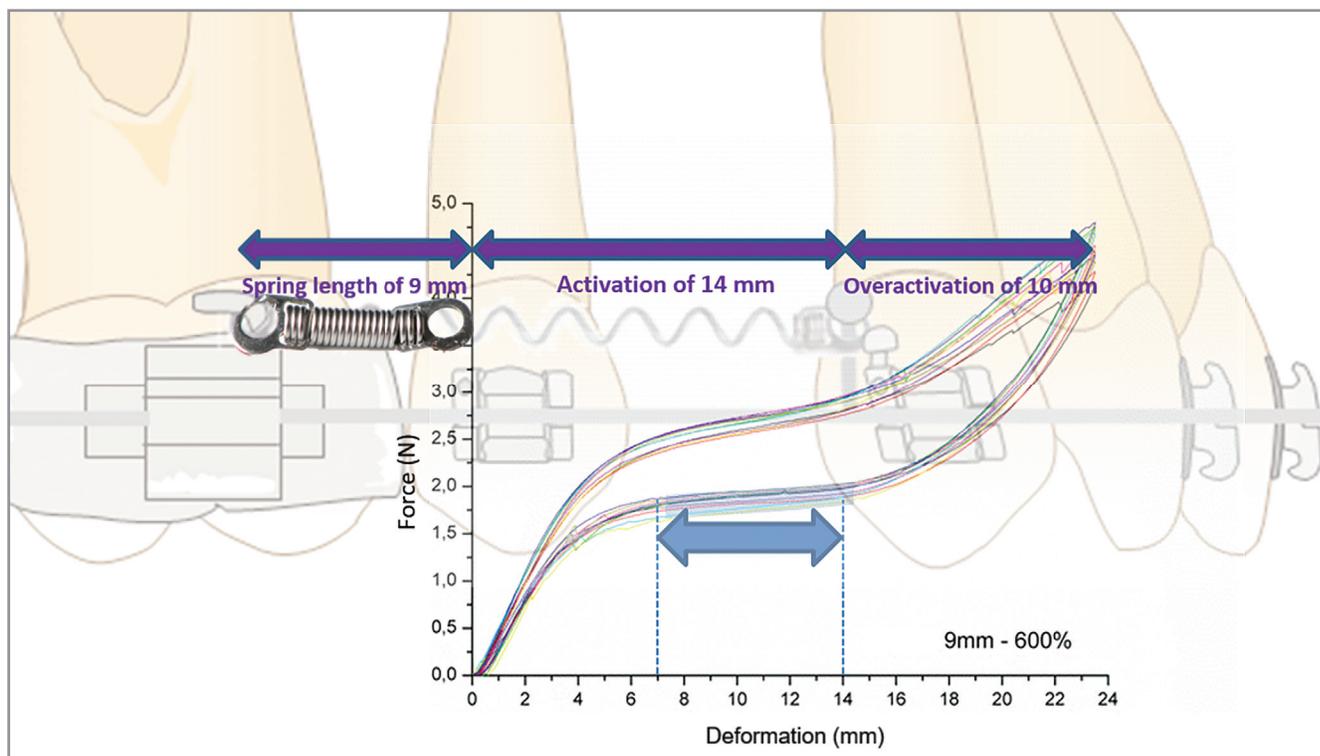


Figure 7 - A 9-mm long nickel-titanium spring (3.9mm of nickel-titanium portion) activated 23.4mm, or 600% the length of its SE material. A spam of activation from 14mm to 7mm is shown by the blue arrow. Note that a pseudo-plateau can be used in this situation only if the spring is overactivated 10mm beyond its affixation. The amount of overactivation will depend on the spring's total length, the length of nickel-titanium portion, and the interbracket distance.

teau is not produced. Even if SIMT is achieved when a shorter spring is used (Fig 6), there is a sudden drop of force in the beginning of reverse transformation, which would not allow constant force. The spring in this situation could be very flexible, but not superelastic on that 7-mm range of activation. The solution would be either to produce a longer spring, adding to the eyelets and not to the nickel-titanium portion,¹⁷ or to overactivate the springs, as already mentioned (Fig 7). That would allow a window of activation which would use a long enough pseudo-plateau during space closure, escaping from the sudden drop of force, as depicted by Figure 6. Activating the spring only up to 14 mm, and not overactivating it on this particular situation (Fig 7), would include the sudden drop of force characteristically seen in the beginning of the reverse SIMT up to 7 mm of deactivation spam, similar to what is shown in Figure 6. The force, therefore, would not be as continuous as the one produced when overactivating the spring during space closure.

All springs were tested at 37°C, as mentioned in the Methods section, according to the American Dental Association specification of 2006.¹² That was necessary because shape-memory alloys respond differently to a given temperature^{14,18} and, therefore, it was the objective of this paper to know how nickel-titanium closed coil springs would deform at mouth temperature. When one of those alloys, nickel-titanium

included, is below its Af temperature, some martensite is stable and will allow deformation that would not exist at a higher temperature; i.e., above Af. Even though the springs were tested at 37°C, not all characteristics of the oral cavity could be mimicked, which is one of the limitations of this study. This is important because it is known that the oral cavity could contribute further to the deformation of springs.¹⁹

CONCLUSIONS

» The majority of springs had a similar amount of deformation from the moment they became superelastic, from around 400% of activation up to 700% of activation, in relation to the length of the nickel-titanium portion present in the closed coil springs, without rupturing.

» Subgroups 4B, 4C, 4D, and 4E had a similar amount of deformation up to 1000% of activation (32 mm) without rupturing.

Author contributions

Conception or design of the study: JMSNR, LGV, LPM. Data acquisition, analysis or interpretation: CIVV, JMSNR, LGV. Writing the article: CIVV, RPM. Critical revision of the article: LGV, LPM. Final approval of the article: JMSNR, LPM, RPM. Obtained funding: CIVV, LPM. Overall responsibility: RPM.

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