An efficient indoor ray-tracing propagation model with a *quasi*-3D approach

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Abstract— This paper presents an indoor propagation model that uses image-based ray-tracing with a *quasi-3D* approach. A fast 2D algorithm finds the most relevant rays lying in the horizontal plan of the indoor environment. Then, every path is converted into five rays that lie in the vertical plane. As a consequence, the thirddimension effect is considered in the field computation. Comparisons were made with measurements for a typical indoor scenario and the *quasi-3D* approach results showed to be as good as the results obtained by a full 3D ray-tracing tool. With this approach, it is possible to have a computational cost comparable to that of a 2D algorithm, without significant impairment in the accuracy compared to results obtained with a 3D tool.

Index Terms— Indoor propagation, quasi-3D, ray-tracing.

I. INTRODUCTION

With the impressive growth in wireless systems due to the new generation technologies, the need for a suitable design before their implantation becomes essential. Hence, the use of an electromagnetic prediction model represents an important design procedure.

Ray-tracing models using Geometrical Optic (GO) and Uniform Theory of Diffraction (UTD) present good results both in indoor and outdoor urban environments [1]-[5]. It is worth to point out that, in indoor scenarios, it is common to use ray-tracing models neglecting diffraction [6], [7]. Two-dimensional models have been an interesting option, providing good results for certain scenarios. However, in general, these 2D models yield large errors due, for example, to height differences between transmitting and receiving antennas.

This paper presents a *quasi-3D* ray-tracing model valid for indoor environment, which we named RTQ3D-indoor. This algorithm uses the Method of Images to find all paths on the horizontal plane and to convert each 2D trajectory into five *quasi-3D* rays lying in the vertical plane.

The environment description in RTQ3D-indoor model relies on horizontal plan data, but considering also transmitting and receiving antennas heights as well as roof height from the ground. The rays in horizontal plane are traced considering a specific procedure for transmitted rays though walls [6]. Reflections up to second-order are also considered on the horizontal plane. On the vertical plane, this algorithm considers not only the first-order reflection in the ground, but also the ceiling reflection. The second-order reflections (roof-ground and ground-roof reflections) are also taken into account.

The following section presents the proposed algorithm. The RTQ3D-indoor model validation is presented in section III by comparisons with full 3D RT model and with measurements [1], [11] in typical indoor scenarios. Finally, Section IV presents a brief conclusion of this paper.

II. THE RTQ3D-INDOOR MODEL

Firstly, the RTQ3D-indoor model uses 2D ray-tracing algorithm based on the Theory of Images for build a "tree of images" and find the various reflected rays for a given scenario. Thus, the input database is described in the horizontal plane, but adding the ceiling height from the floor and the transmitting (base stations) and receiving (user terminals) antennas heights.

To consider the transmission rays through the obstacles (walls, doors, windows, etc.), the model adopts the approach proposed in [6]. This approach takes into account the shift due to the double refraction (air-obstacle-air) occurred when a ray crosses an obstacle. It allows accurate transmitted field computation.

As other ray-tracing models applied to indoor applications [7], the proposed RTQ3D-indoor algorithm neglects diffractions in the total field computation. Additionally, the model considers up to second-order reflections. It allows increasing ray-tracing speed without significant loss of accuracy. Indeed, higher-order reflections contribute little to the total field (since they correspond to fields that undergo greater attenuation), but greatly increase the computational cost. Moreover, the significant decreasing in the number of intersections tests during the ray-tracing calculation is done by using an acceleration technique, namely, Space Volumetric Partitioning (SVP) [1], [8], [13].

For two-dimensional conversion of trajectories in paths closer to reality, it is common to use *quasi*-3D strategies. In these cases, 2D rays (in the horizontal plane) are also considered in a vertical plane. Fig. 1 shows an example of converting a 2D trajectory to a *quasi*-3D, as presented in [9]. A single propagation ray in the horizontal plane – which can suffer reflection (r), diffraction (D) and other reflection (r) – has two 3D paths: the direct path and a ground-reflected path. Thus, each horizontal path is converted into two ones lying in the vertical plane: the direct path and the path reflected on the ground.



Fig. 1. Example of converting a 2D path into two quasi-3D paths [4], [9].

In [10], a similar approach (2.5D model) is applied to indoor environments, but adopting the Shooting and Bouncing Rays (SBR) method. However, this approach tends to be insufficient to

describe the indoor environments phenomena, since the ceiling reflections are as important as the reflections in the ground. In [12], the authors have proposed a *quasi-3D* indoor prediction model that also uses Image Theory Ray-Tracing method, but they have not detailed the construction of *quasi-3D* rays and how the exact or approached path of transmitted rays through walls (due to double refraction) is considered. The authors of [12] underscore that their *quasi-3D* model took just 1% of the computational time compared to a traditional full 3D model.

To extend the *quasi*-3D analysis using the method of images to indoor environments and adopting an efficient transmitted rays through wall consideration (due to double refraction) [6], the RTQ3Dindoor algorithm is now presented. Since its application is in indoor environments – and given the considerations of the transmitting antenna height, receiving antenna height and ceiling height from the ground – this algorithm takes into account not only the first-order ground reflections, but also the ceiling reflections. Additionally, from vertical plane viewpoint, the proposed model also considers second-order reflections: ceiling-ground and ground-ceiling ones (see Fig 2b).



Fig. 2. Conversion of a 2D path to five *quasi*-3D paths using the RTQ3D-indoor algorithm: a) horizontal plane; b) vertical plane.

Brazilian Microwave and Optoelectronics Society-SBMO Brazilian Society of Electromagnetism-SBMag received 14 Apr 2014; for review 22 Apr 2014; accepted 28 July 2014 © 2014 SBMO/SBMag ISSN 2179-1074 According to the example of Fig. 2, the ray-tracing algorithm applied on *quasi* three-dimensional indoor environments (RTQ3D-indoor) converts a given path initially obtained from the RT 2D algorithm in five trajectories:

(i) direct path (from the viewpoint of a vertical plane);

(ii) the ground reflected path;

(iii) the ceiling reflected path;

(iv) the path reflected on the ground and on the ceiling; and

(v) the path reflected first on the ceiling and then on the ground.

In fact, the paths obtained by the 2D algorithm are the 3D actual path projections on the horizontal plane. Thus, all the reflection angles initially obtained by the 2D algorithm must be properly corrected. For that, we take into account the slope angle of all the new five paths, in order to avoid errors, for example, in the calculation of reflection and transmission coefficients. It is worth also mentioning that obstacles are interpreted by the algorithm as having the same height (ground-ceiling) and being perpendicular to the ground, which represents a limitation when compared with a full 3D model.

Once all the rays are traced, from Geometric Optics we obtain an approximated solution of the total field at a reception point by adding the fields due to all the rays. Therefore, the electric field in a given reception point (due to rays leaving from a transmitter and reaching the considered reception point) is given by:

$$\vec{E}_{R} = A_{s}e^{-j\beta s} \left\{ \prod_{i} \Gamma_{i} \right\} \left\{ \prod_{k} T_{k} \right\} \vec{E}_{o}$$
⁽¹⁾

where $A_s = \rho / (s + \rho)$ is the spreading factor for a spherical wave; *s* is the total distance (in air) of the path from a reference point to the reception point; ρ is the distance between the transmitter and the reference point; \vec{E}_o is the electric field calculated at the reference point considering a propagation in free space (in the far field region); βs is the total phase shift along the propagation path in air; Γ_i is the reflection coefficient matrix due to the *i*-th reflection and T_k is the transmission coefficient due to *k*-th transmission of the ray (considering the propagation through the obstacles [6]). These coefficient matrices take into account the components of vertical and horizontal polarization. Hence, not only the amplitude and phase, but also the polarization is considered on total field computation, obtained by field contributions due to relevant rays.

III. RESULTS

To validate the RTQ3D-indoor algorithm, comparisons are made in a typical indoor scenario as presented in subsection A. In subsection B, we have applied our model in order to illustrate a 900 MHz and 2100 MHz wave propagation prediction in a practical scenario.

A. Comparison and validation

We analyzed the real indoor scenario presented in [1], [11], whose 3D view is shown in Fig. 3. The geometric and electromagnetic characteristics of the environment are used as input to the RTQ3D-indoor algorithm. According to [1], the walls have the same electrical properties ($\varepsilon_r = 4.44$, $\sigma = 0.08$ S/m, and $\mu_r = 1.0$) and the height from ground to ceiling is 2.9 m.



Fig. 3. Three-dimensional view of the indoor scenario.

Fig. 4 shows the floor plan with the respective measurement routes that are adopted to make comparisons. Only this floor is considered in the simulation. As noted in [1], such routes are properly distributed to enable a field evaluation under both line-of-sight (LOS) and non-line-of-sight (NLOS) conditions. Then, this scenario allows assessing the influence of transmitted rays through obstacles on the computed fields.



Fig. 4. Top view of the indoor scenario [1] with the five routes analyzed.

Brazilian Microwave and Optoelectronics Society-SBMO Brazilian Society of Electromagnetism-SBMag received 14 Apr 2014; for review 22 Apr 2014; accepted 28 July 2014 © 2014 SBMO/SBMag ISSN 2179-1074 For routes 1 to 3, the transmitter is positioned at the point "Tx1", and for routes 4 and 5, the transmitter was located at "Tx2". As described in [1], the transmitting antenna is vertically polarized and its radiation pattern (E-plane and H-plane) is shown in Fig. 5. The antennas at reception points are simulated as vertically polarized short dipoles. In all cases, the transmitting antenna (base station) is located at 1.7 m of above the ground and the receiving antennas (along the evaluation routes) are located at 0.6 m height.



Fig. 5. Transmitting antenna radiation pattern.

As in [1], for simulations where the transmitter is positioned at the point Tx1, the transmitting antenna is oriented with direction of maximum radiation pointed to + x, while for the simulations that the transmitter is placed in Tx2, the antenna is pointed at the -z direction. These features are included as input data of the RTQ3D-indoor simulation.

The results for each route are shown in Fig. 6 to Fig. 10. These figures show the comparisons between measurements and simulations using a full 3D RT model, both presented in [1], with the results obtained with the proposed RTQ3D-indoor algorithm.



Fig. 6. Results corresponding to evaluation along route n° 1.

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Fig. 7. Results corresponding to evaluation along route n° 2.



Fig. 8. Results corresponding to evaluation along route n° 3.



Fig. 9. Results corresponding to evaluation along route n° 4.

Brazilian Microwave and Optoelectronics Society-SBMO Brazilian Society of Electromagnetism-SBMag received 14 Apr 2014; for review 22 Apr 2014; accepted 28 July 2014 © 2014 SBMO/SBMag ISSN 2179-1074 These results demonstrate the validity of the RTQ3D-indoor developed tool. Indeed, the results obtained through the RTQ3D-indoor model agree well with the measurements and are as good as the results obtained with a full RT 3D model.

To illustrate the error that can be generated when the 3D effects are not considered, Fig. 10 (relating to route 5) shows also the results obtained using a two-dimensional ray-tracing algorithm (2D RT). Clearly, the use of the 2D RT algorithm presents higher deviations from the measurements.



Fig. 10. Results corresponding to evaluation along route n° 5.

Route	RT full 3D		RTQ3D-indoor	
	Error (dB)	SD (dB)	Error	SD (dB)
1	-1,37	7,04	0,35	6,02
2	1,65	7,96	-3,96	7,01
3	3,38	6,79	-3,84	7,04
4	-1,66	7,29	3,67	6,57
5	-3,59	8,33	-2,44	7,91

TABLE I. MEAN ERROR AND STANDARD DEVIATION FOR THE CONSIDERED ROUTES.

Table I presents comparative numerical values, confirming the validity of the RTQ3D-indoor algorithm for this type of environment. In order to compare the results, we use the same quantities presented in [1]: the mean error and the standard deviation (SD), both in dB. For the RT 2D simulation, performed only for route 5, the values obtained for mean error and standard deviation are 10.23 dB and 8.18 dB, respectively.

B. Illustration in a practical scenario

A practical scenario, presented in Fig. 11, was used to illustrate the capacity of the RTQ3D-indoor model for wave propagation prediction.



Fig. 11. View of the practical indoor environment.

This scenario represents the third floor of a large shopping mall located in the city of Florianopolis, Brazil. The analysis was performed considering a single floor, which has about 10,000 m^2 . As a result of the prediction, it was obtained the received power color mappings for the frequencies 900 MHz and 2100 MHz, as shown in Fig. 12 and Fig. 13, respectively.



Fig. 12. Received power mapping for 900 MHz.



Fig. 13. Received power mapping for 2100 MHz.

IV. CONCLUSION

This paper presents an electromagnetic prediction model for indoor environments based on *quasi-*3D ray-tracing method. Its validation relies on comparisons with measurements as well as a full 3D ray-tracing algorithm results from literature. The results are very consistent compared to those obtained with a full 3D RT, but with a much lower computational cost, since the computation time of RTQ3D-indoor was similar to that of a 2D algorithm. Wave propagation predictions were made for a real indoor environment and the received power mappings were presented.

We conclude that the presented method can be an effective tool in the design of indoor wireless systems. One possible application would be, for example, the use of the proposed method in combination with an optimization method to find the best antenna placement in an indoor scenario, in order to get a more uniform illumination, reducing shadow areas [14].Finally, it is worth noting that ray-tracing method is used to perform electromagnetic predictions at a given frequency. This is not an issue, since narrowband analysis have been traditionally used to coverage prediction. Nevertheless, ray-tracing method can be easily used to broadband channels evaluation [15] when necessary.

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